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Microsoft

Tessellation of Displaced Subdivision Surfaces in DX11

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Developer Technology - NVIDIA



Overview

- Motivation
- Subdivision Surfaces
 - Control point evaluation
 - Surface evaluation
- Displacement Mapping
- Content Creation



Motivation

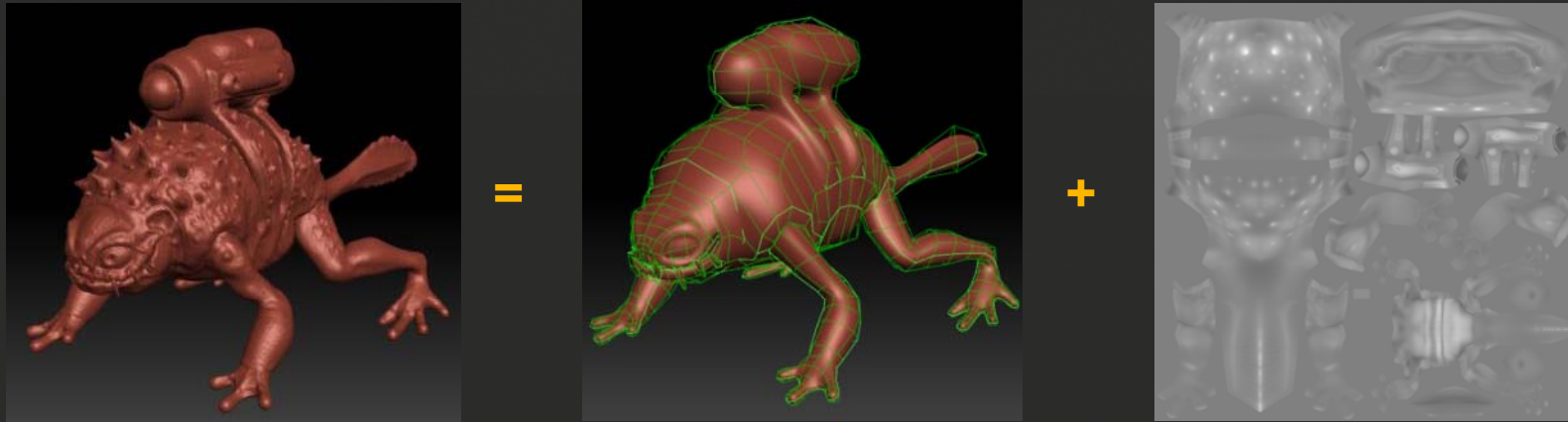


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Compression

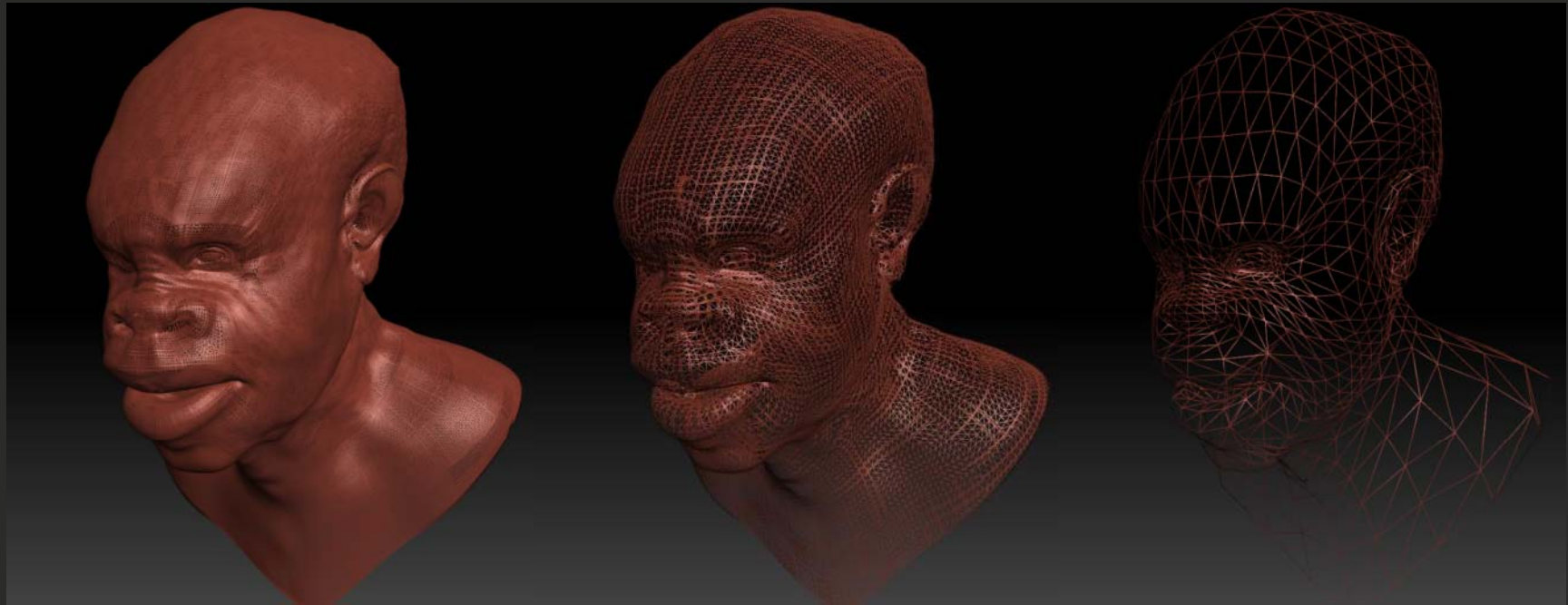
- Save memory and bandwidth
 - Memory is the main bottleneck to render highly detailed surfaces



	Level 8	Level 16	Level 32	Level 64
Regular Triangle Mesh	16MB	59MB	236MB	943MB
Displaced Subdivision Surface	1.9MB	7.5MB	30MB	118MB

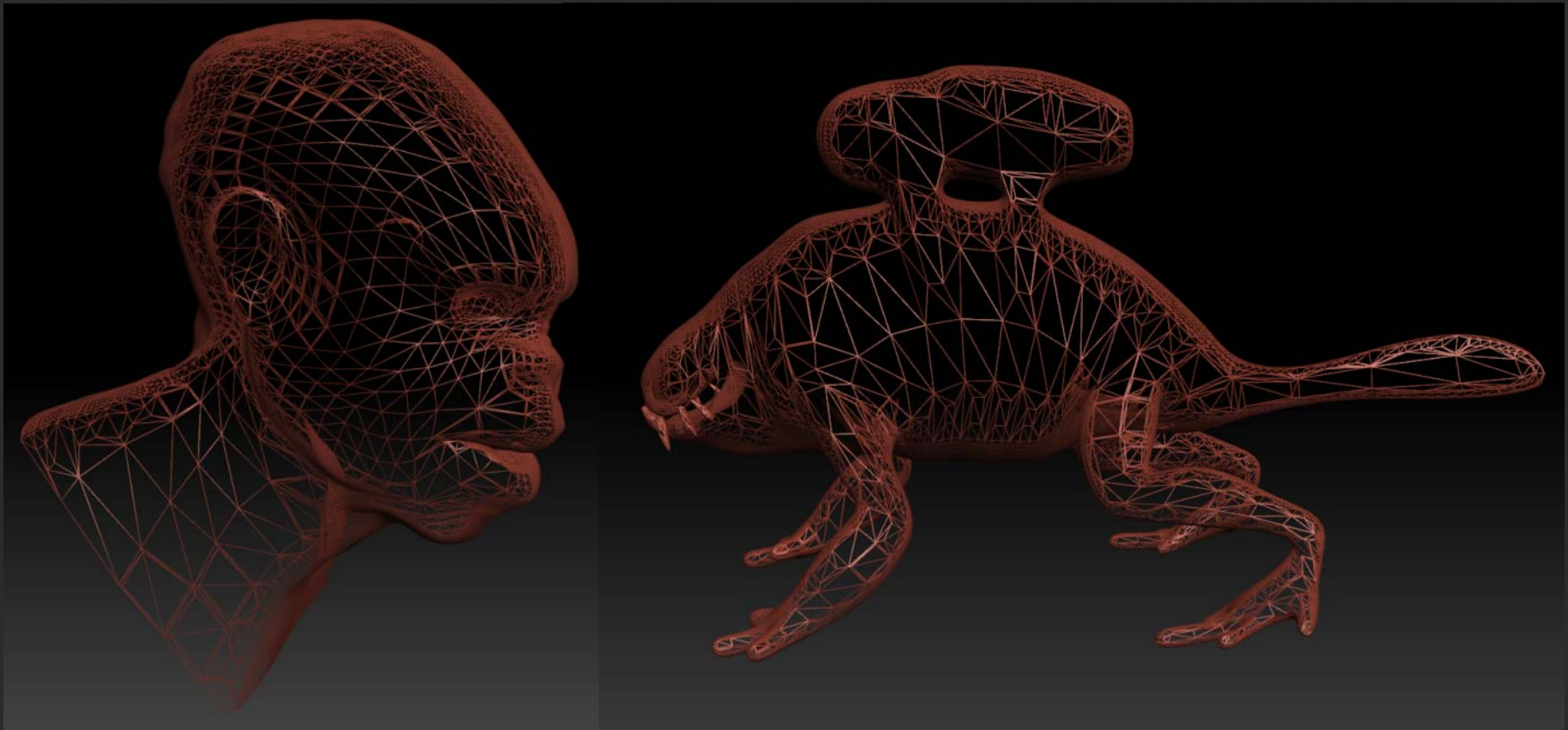
Scalability

- Continuous Level of Detail



Scalability

- View Dependent Level of Detail



Animation & Simulation

- Perform Expensive Computations at lower frequency:
 - Realistic animation: blend shapes, morph targets, etc.



- Physics, collision detection, soft body dynamics, etc.



Goal

- Enable unprecedented visuals:
 - Highly detailed characters
 - Realistic animation



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Subdivision Surfaces



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Subdivision Surfaces

- Easy modeling and flexible animation
- Widespread use in the movie industry
- Readily available in modeling and sculpting tools

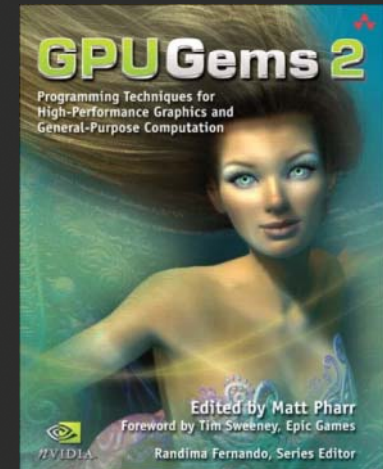


© Pixar Animation Studios 1998



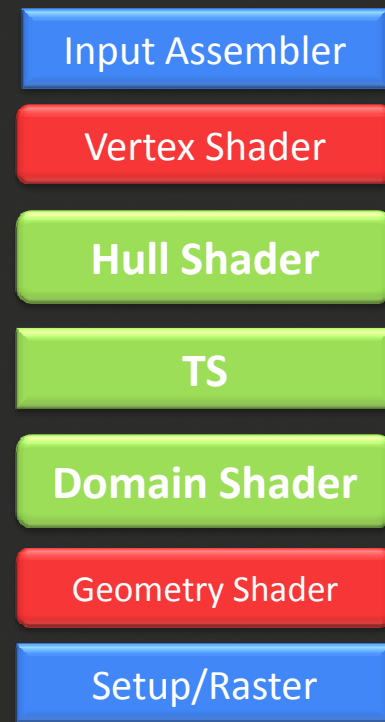
GPU Implementations

- Previous approaches on the GPU:
 - “Adaptive Tessellation of Subdivision Surfaces with Displacement Mapping”, Michael Bunnell
 - Recursive Geometry Shader refinement
- Require multiple passes → Direct evaluation is preferred



Tessellation Pipeline

- Direct3D11 extends Direct3D10 with support for **programmable** tessellation
- Two new shader stages:
 - Hull Shader (HS)
 - Domain Shader (DS)
- One fixed function stage:
 - Tessellator (TS)

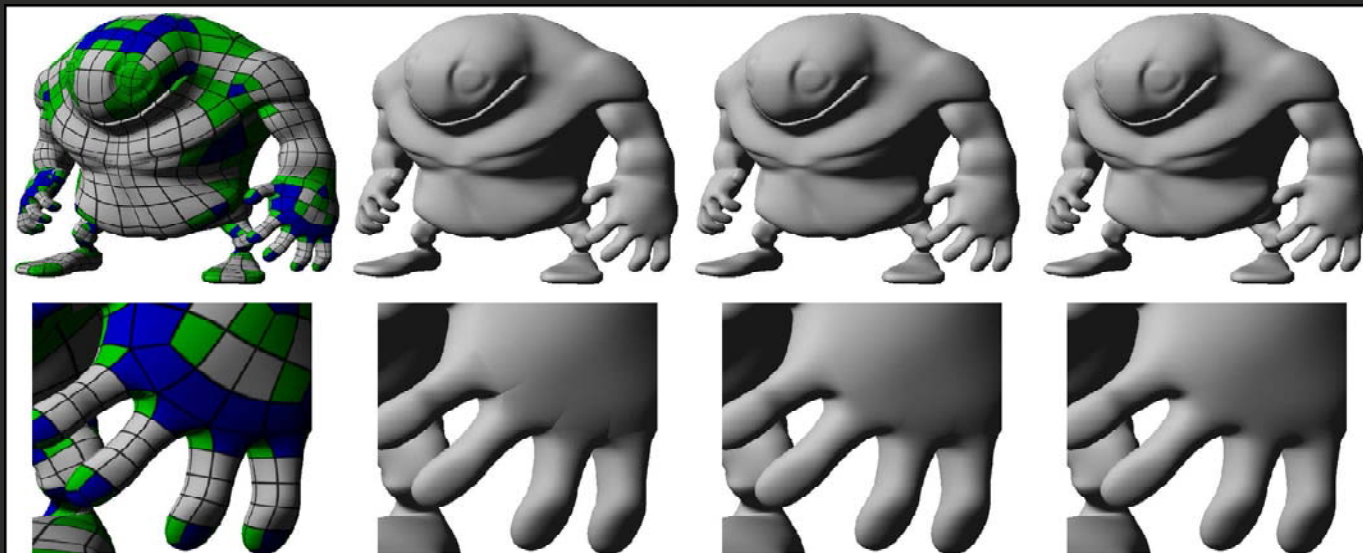


Direct Evaluation of Subdiv. Surfaces

- Jos Stam: “Exact evaluation of Catmull-Clark subdivision surfaces at arbitrary parameter values”
 - Requires extraordinary vertices to be isolated
 - Evaluation is quite expensive
- Jeff Bolz and Peter Schroeder: “Evaluation of Subdivision Surfaces on Programmable Graphics Hardware”
 - Requires pre-computed basis for each topology and each possible tessellation level

Approximating Catmull-Clark Subdivision Surfaces (ACC)

- Developed by Charles Loop and Scott Shaefer:
<http://research.microsoft.com/~cloop/>
- Surface approximated with a Bezier patch and a pair of independent tangent patches



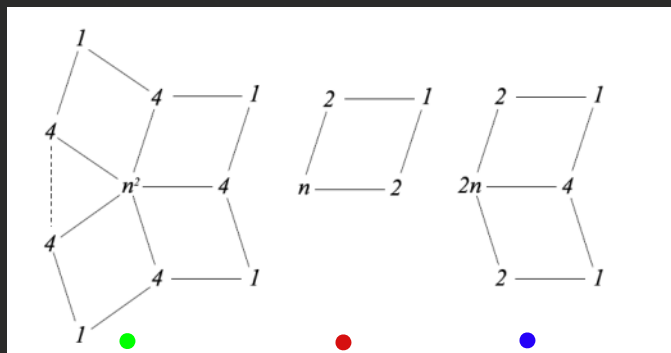
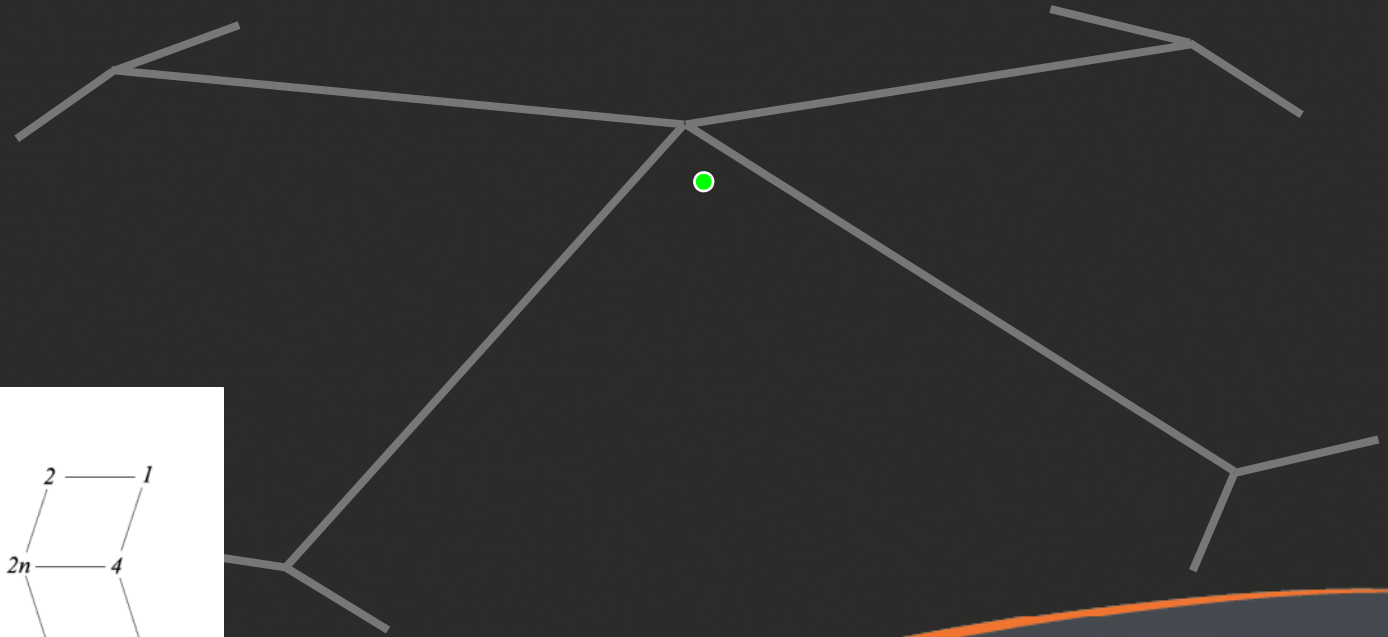
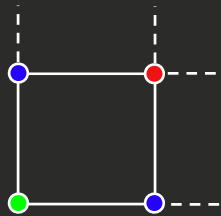
Geometry
Approximation

Geometry/Tangent
Approximation

Subdivision
Surface

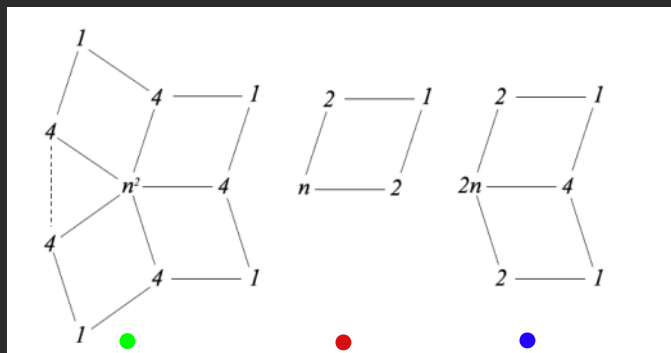
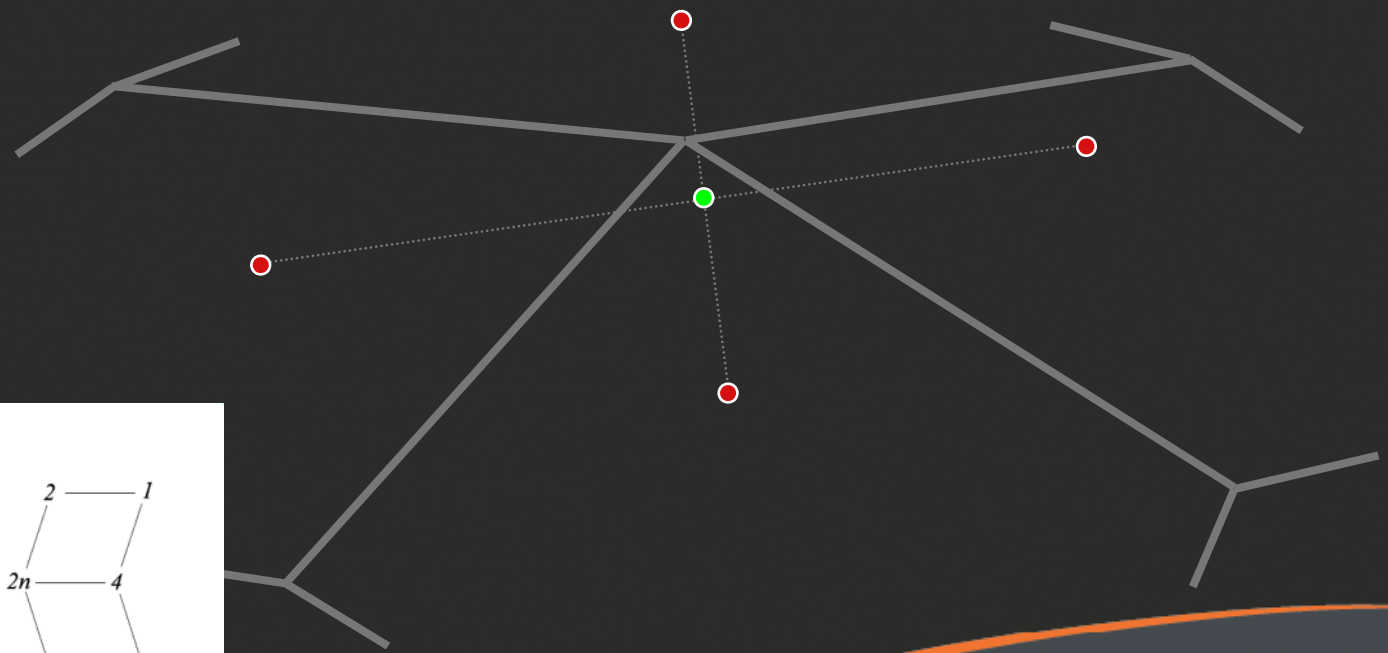
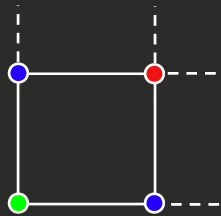
Approximating Catmull-Clark Subdivision Surfaces (ACC)

- Corner control point is vertex projected to limit surface



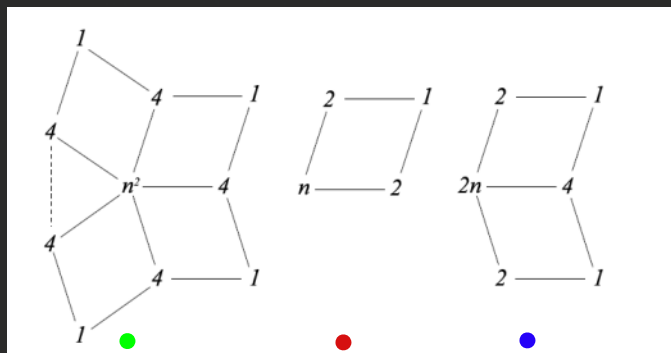
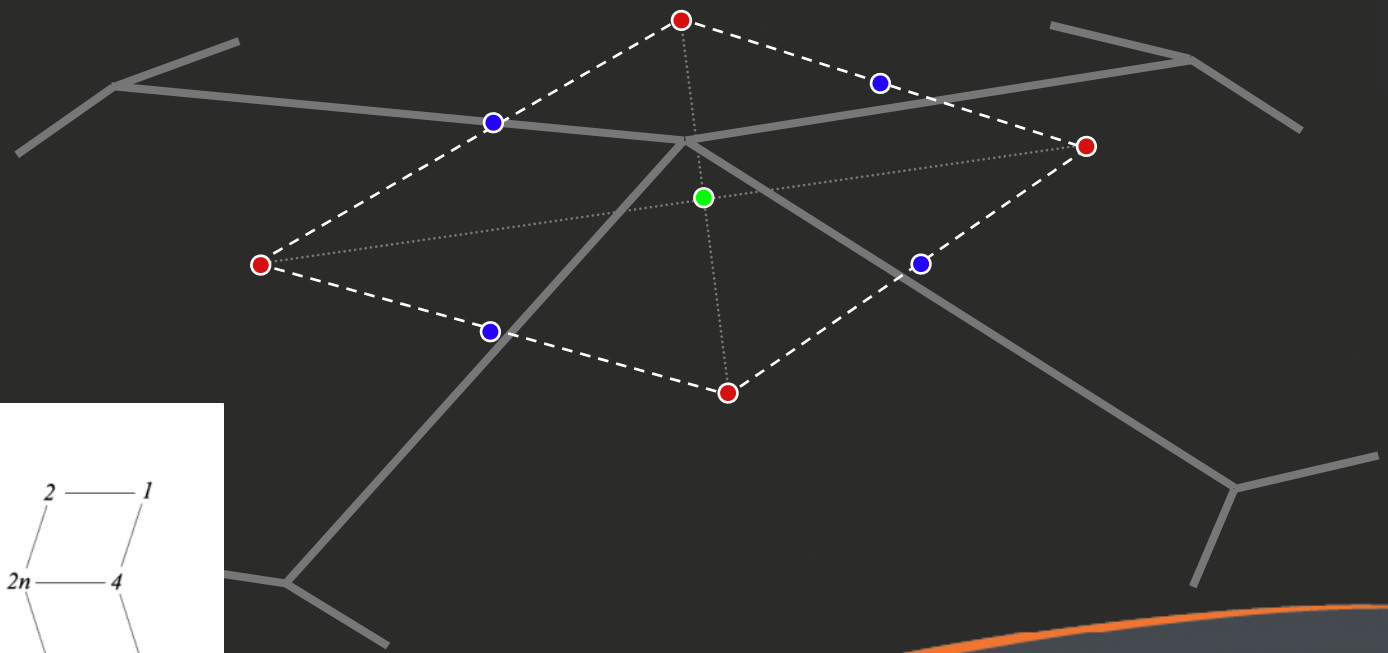
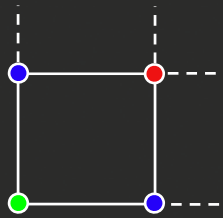
Approximating Catmull-Clark Subdivision Surfaces (ACC)

- Centroid of interior control points equal to limit position of corner vertex



Approximating Catmull-Clark Subdivision Surfaces (ACC)

- Edge vertex midpoint of two interior control points



Approximating Catmull-Clark Subdivision Surfaces (ACC)

- This construction is exact on regular patches, approximate otherwise
- Control tangents are computed similarly:
 - Corner tangents are tangents of the limit surface
 - Boundary tangents are constructed to satisfy continuity condition

Hull Shader (HS)

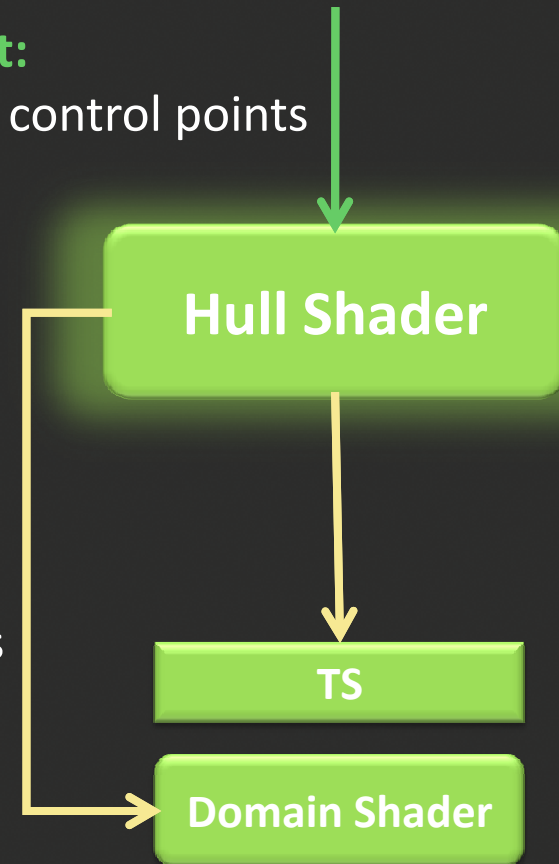
- One invocation per patch
- Parallelized explicitly
 - One thread per control point

HS input:

- [1..32] control points

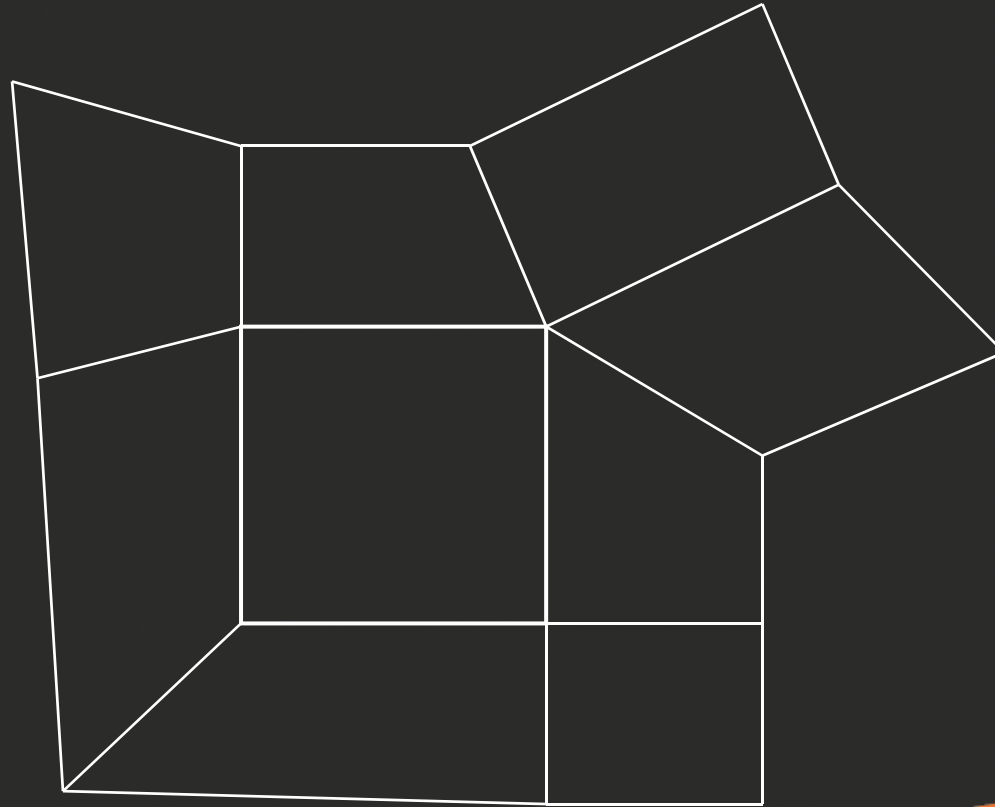
HS output:

- [1..32] control points
- Tessellation factors



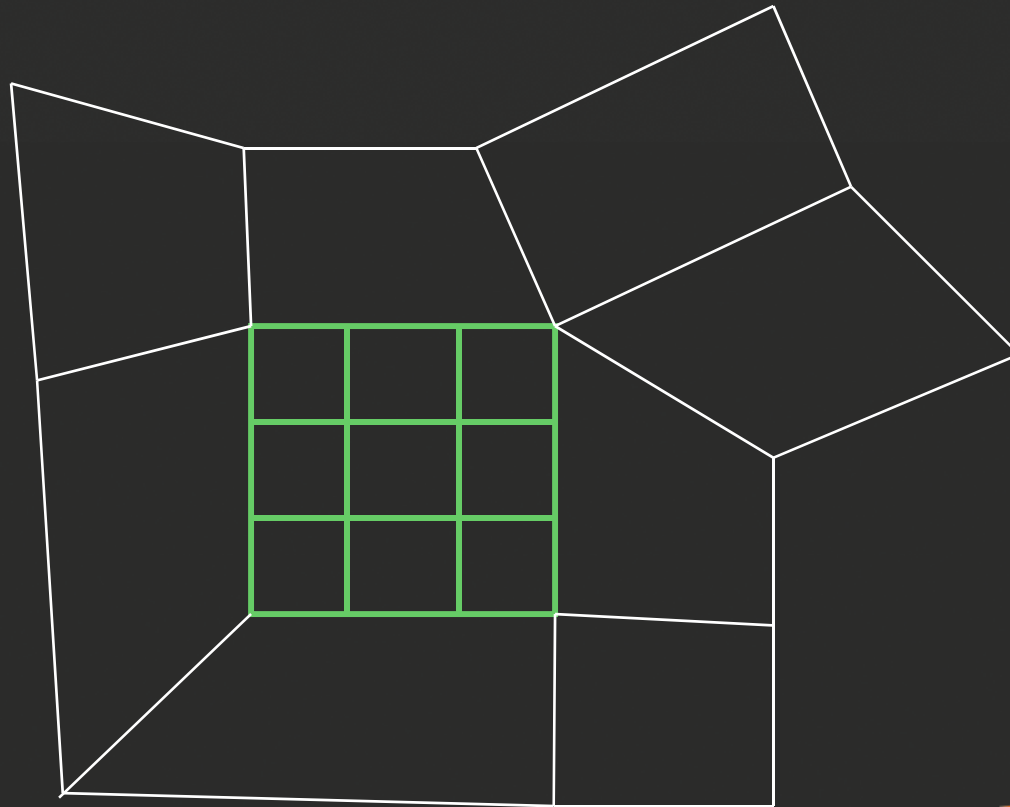
Control Point Evaluation

- HS input is a face and its neighborhood:



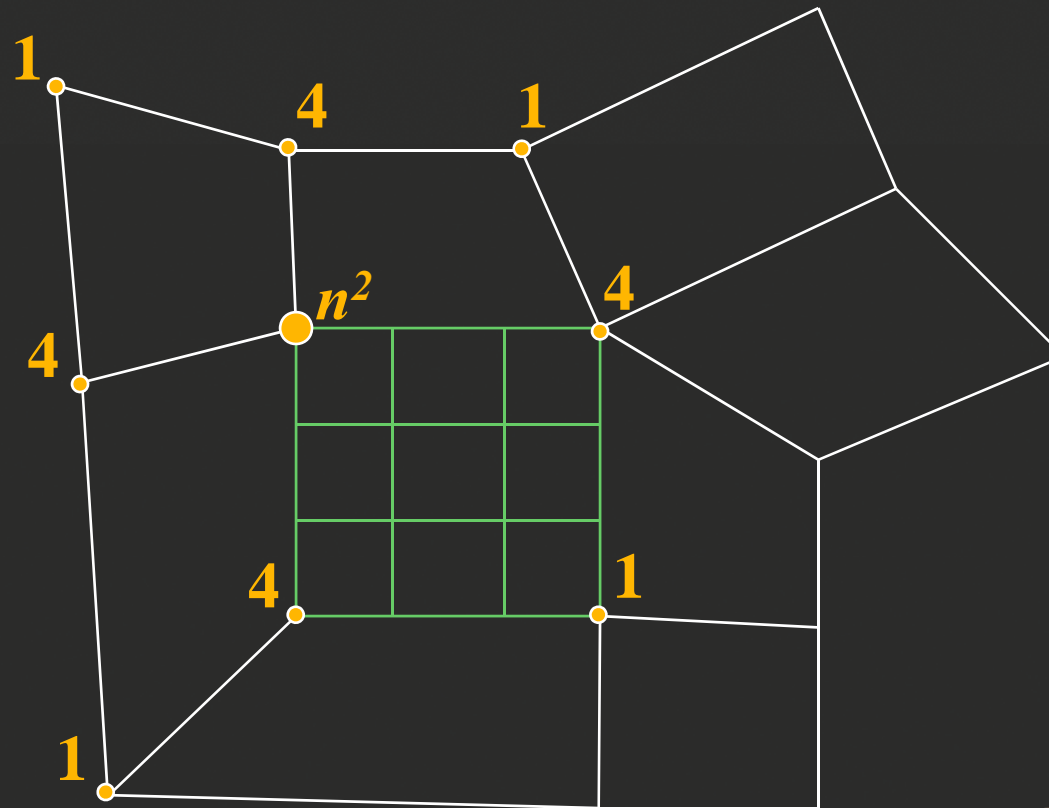
Control Point Evaluation

- HS output is a regular bicubic Bezier patch:



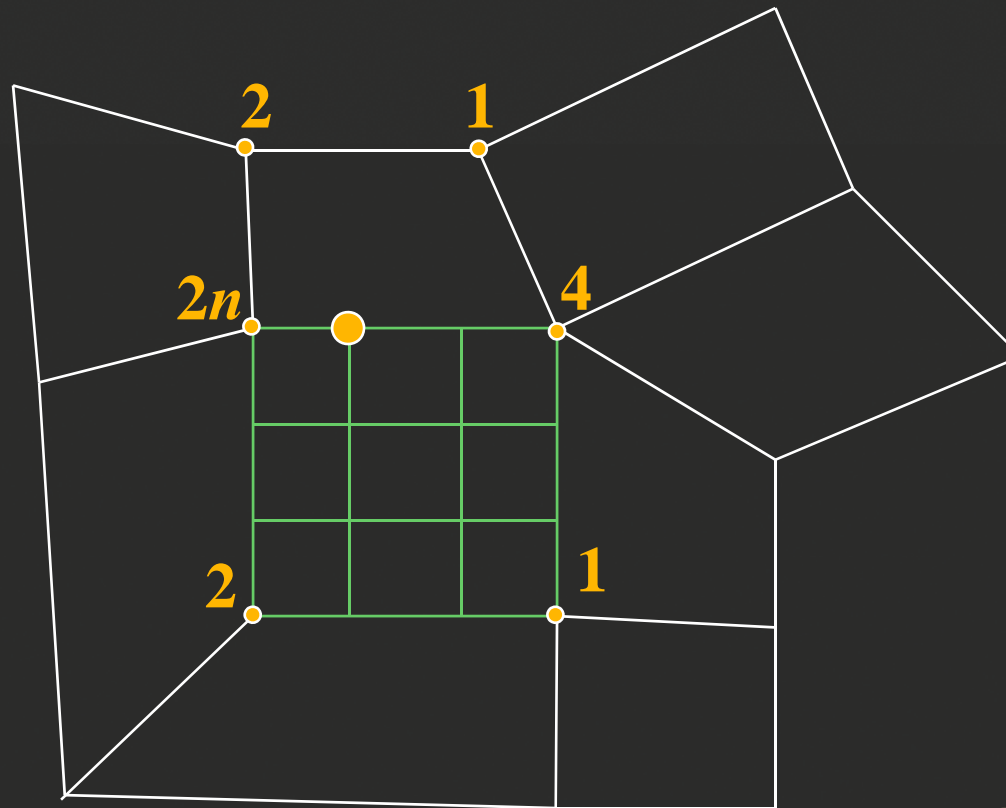
Control Point Evaluation

- Each control point is a linear combination of the neighbor vertices:



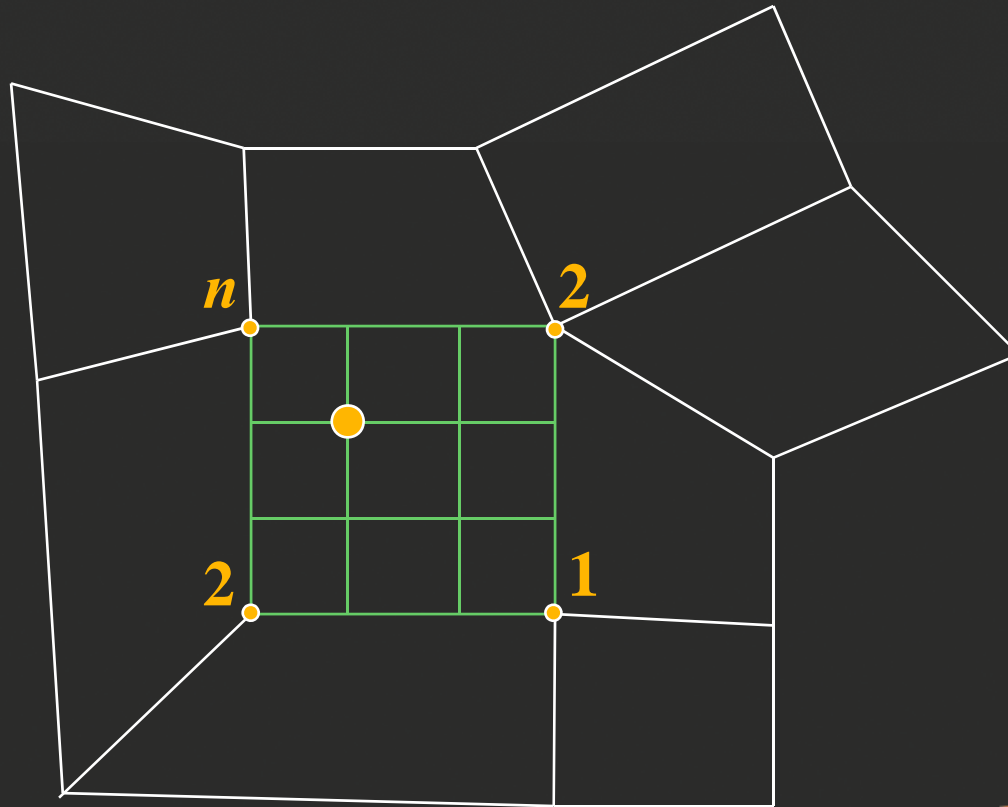
Control Point Evaluation

- Each control point is a linear combination of the neighbor vertices:



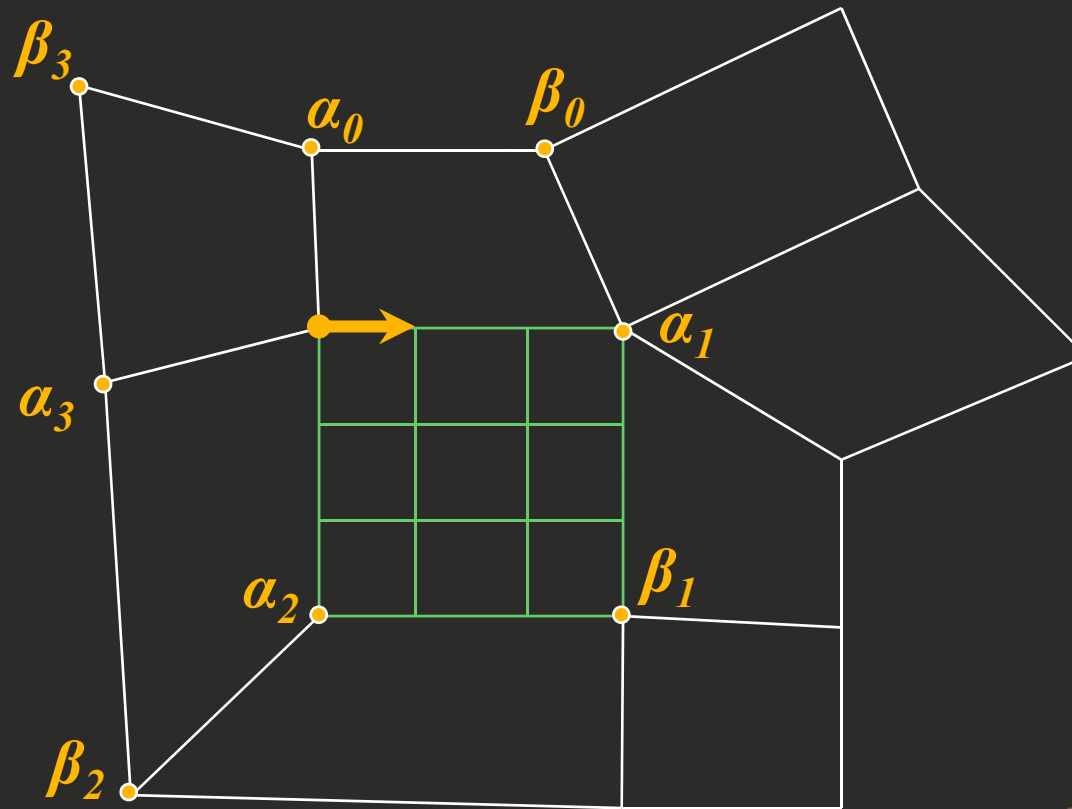
Control Point Evaluation

- Each control point is a linear combination of the neighbor vertices:



Control Point Evaluation

- The same is true for control tangents:



Control Point Evaluation

- In all cases we can evaluate a control point as a **weighted sum**: $P_j = \text{Sum}(W_{ij} * V_i)$
- We can implement that in HS using one thread per control point:

```
global float w[K][16]; } One set of constants for each topology combination
in float3 V[K];      } Input vertices
out float3 pos[16]; } Output control points
```

```
void main() {
    float3 p = 0.0;
    for (int i = 0; i < K; i++) {
        p += V[i] * w[i][threadID]; } For each input vertex Vi
    }
    pos[threadID] = p;
}
```



Control Point Evaluation

- **Pre-compute** stencils for each topology combination
- Each combination rendered in a separate pass:
 - Different topologies have different number of vertices
 - One constant buffer for each set of weights
- Total number of constants depends on number of topology combinations
- It's important to minimize total number of topology combinations



Consistent Control Point Evaluation

- **Shared** control points need to be evaluated “consistently” to avoid cracks in the mesh
 - Sum terms must be added in the same order
 - Define order globally, for example as “position of the vertex in the VB”
 - Use index array to map reordered vertices to stencils

Consistent Control Point Evaluation

```
uniform int vertexIndex[K];
global float w[K][16];
in float3 V[K];
out float3 pos[16];

void main() {
    float3 p = 0.0;
    for (int i = 0; i < K; i++) {
        int idx = vertexIndex[i];
        p += V[i] * w[idx][gl_ThreadID];
    }
    pos[gl_ThreadID] = p;
}
```

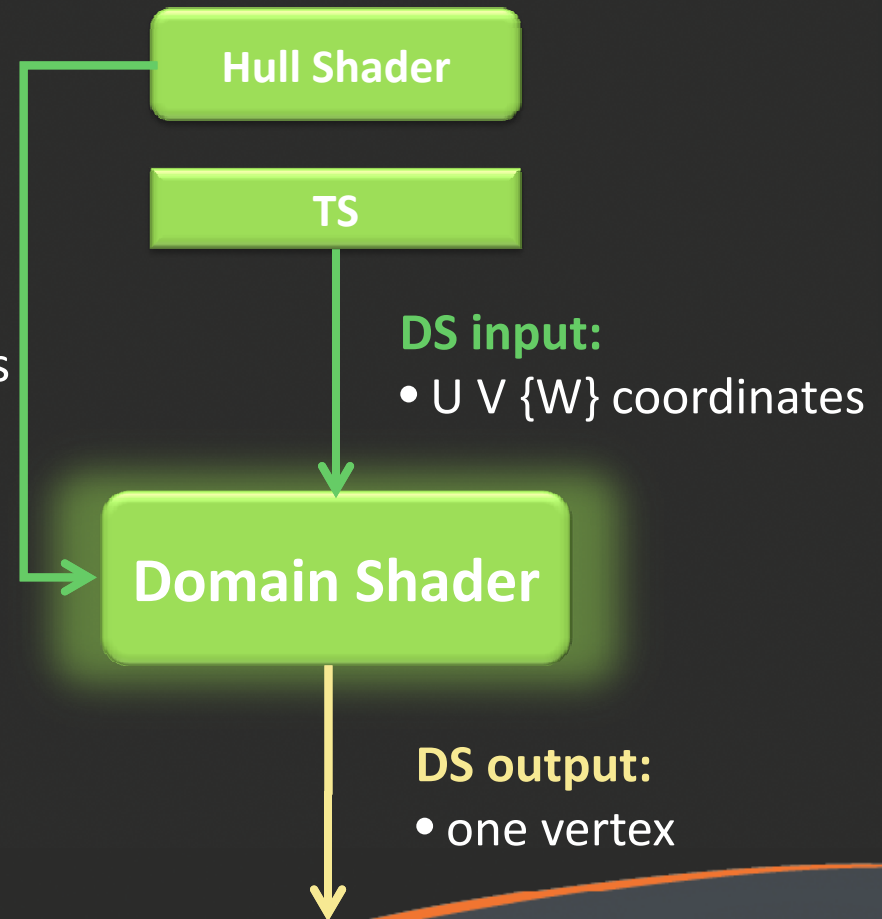


Domain Shader (DS)

- One invocation per generated vertex

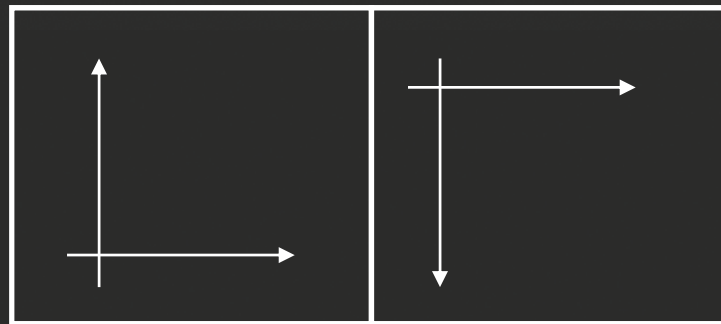
DS input:

- control points
- Tess factors



Surface Evaluation

- DS shader simply evaluates the bicubic Bezier patch and the corresponding tangent fields
- Special care has to be taken to obtain **watertight** results (prevent cracks)
- All computations need to be symmetric along the patch edges



Floating Point Consistency

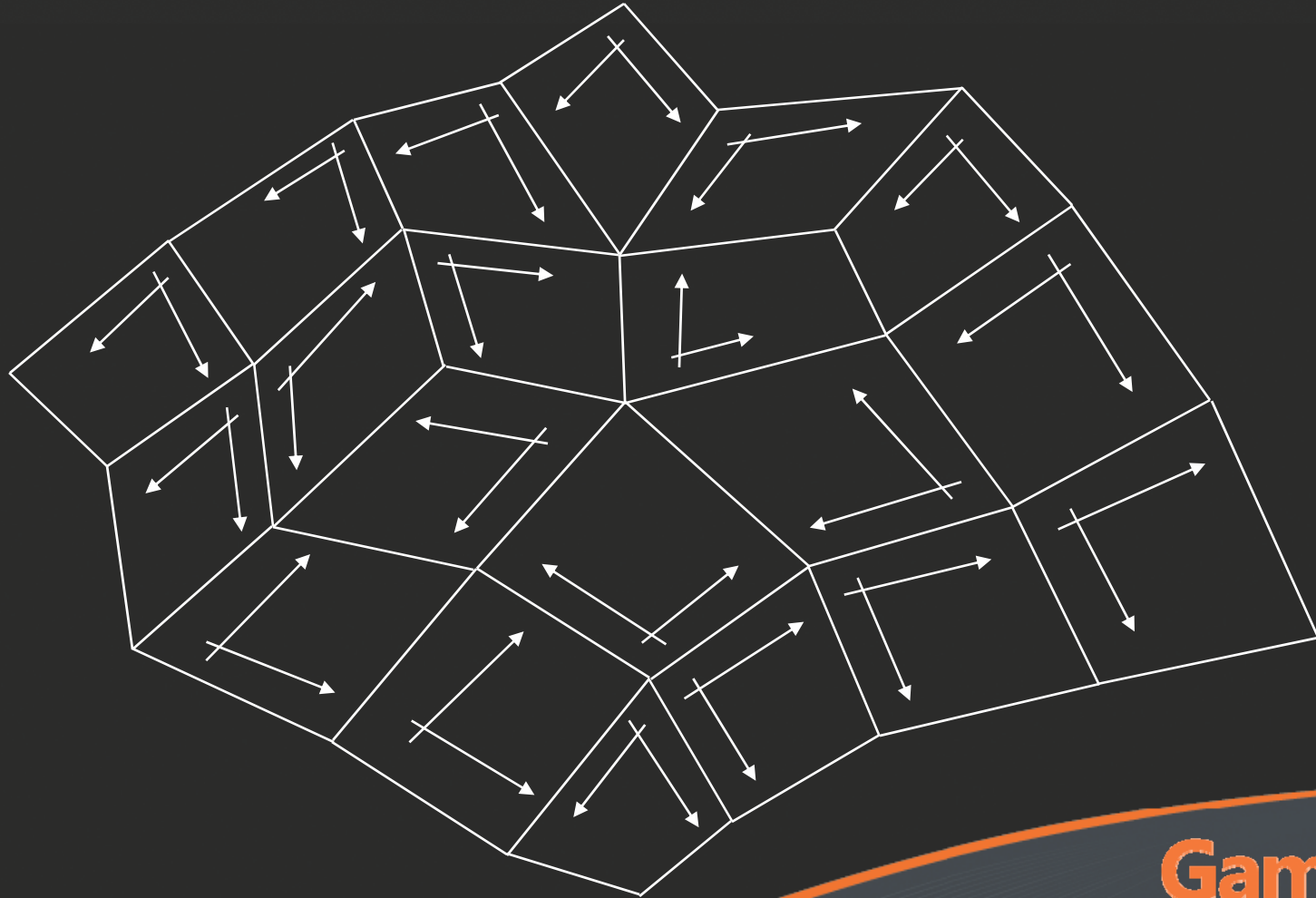
- FP addition is non commutative:
 - $A + B + C + D \neq D + C + B + A$
 - $(A + B) + (C + D) == (D + C) + (B + A)$
- FMA is not equivalent to MUL+ADD
 - $A*a + B*b \rightarrow \text{FMA}(A*a, B, b) \neq \text{FMA}(B*b, A, a)$
- Beware of compiler optimizations
 - Use precise keyword

Surface Evaluation

- Two solutions
 - Reorder faces to make sure all edges have consistent orientations
 - Use symmetric evaluation on the boundaries

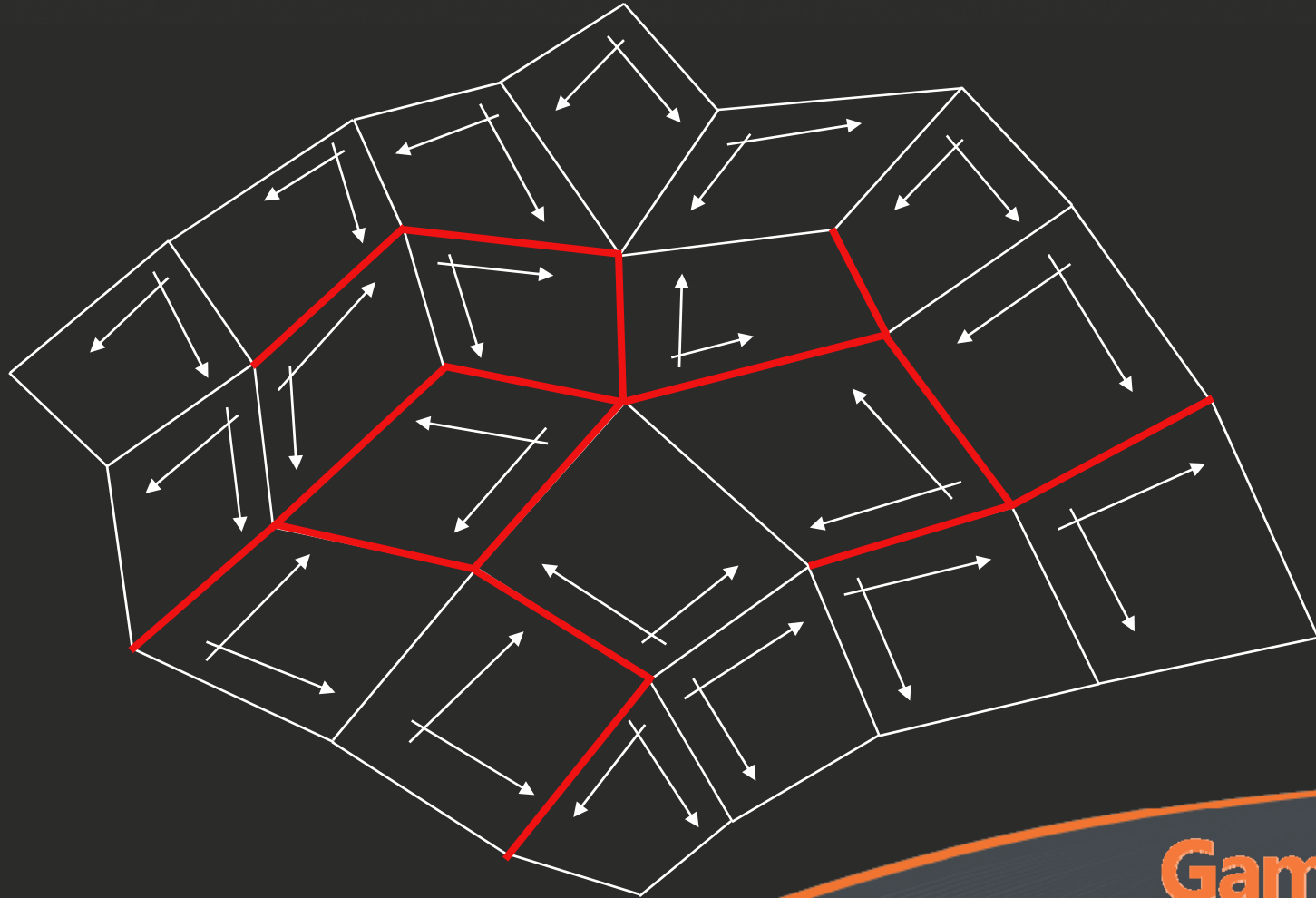
Surface Evaluation

- Faces generally have arbitrary orientations



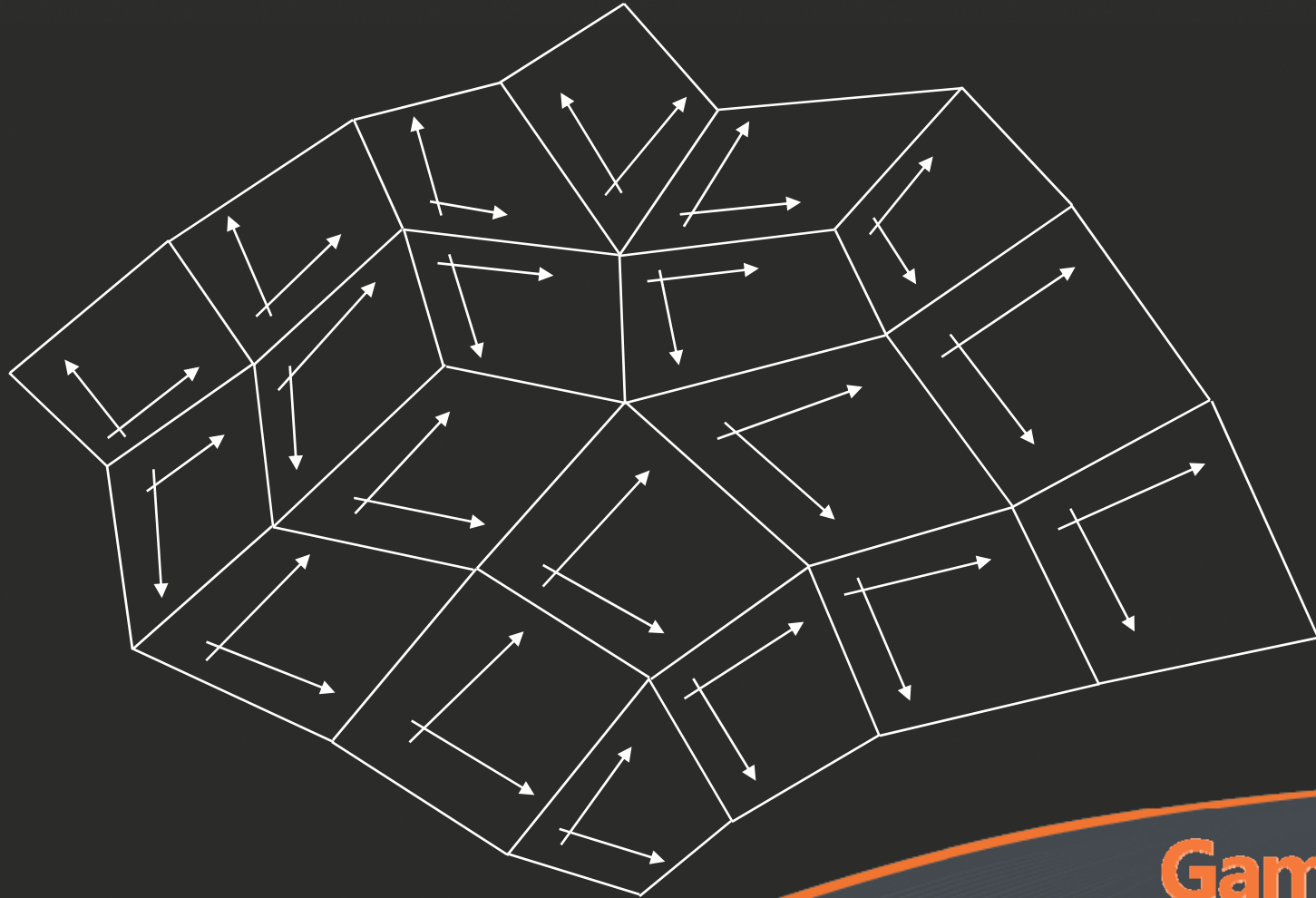
Surface Evaluation

- Many edges have opposite directions



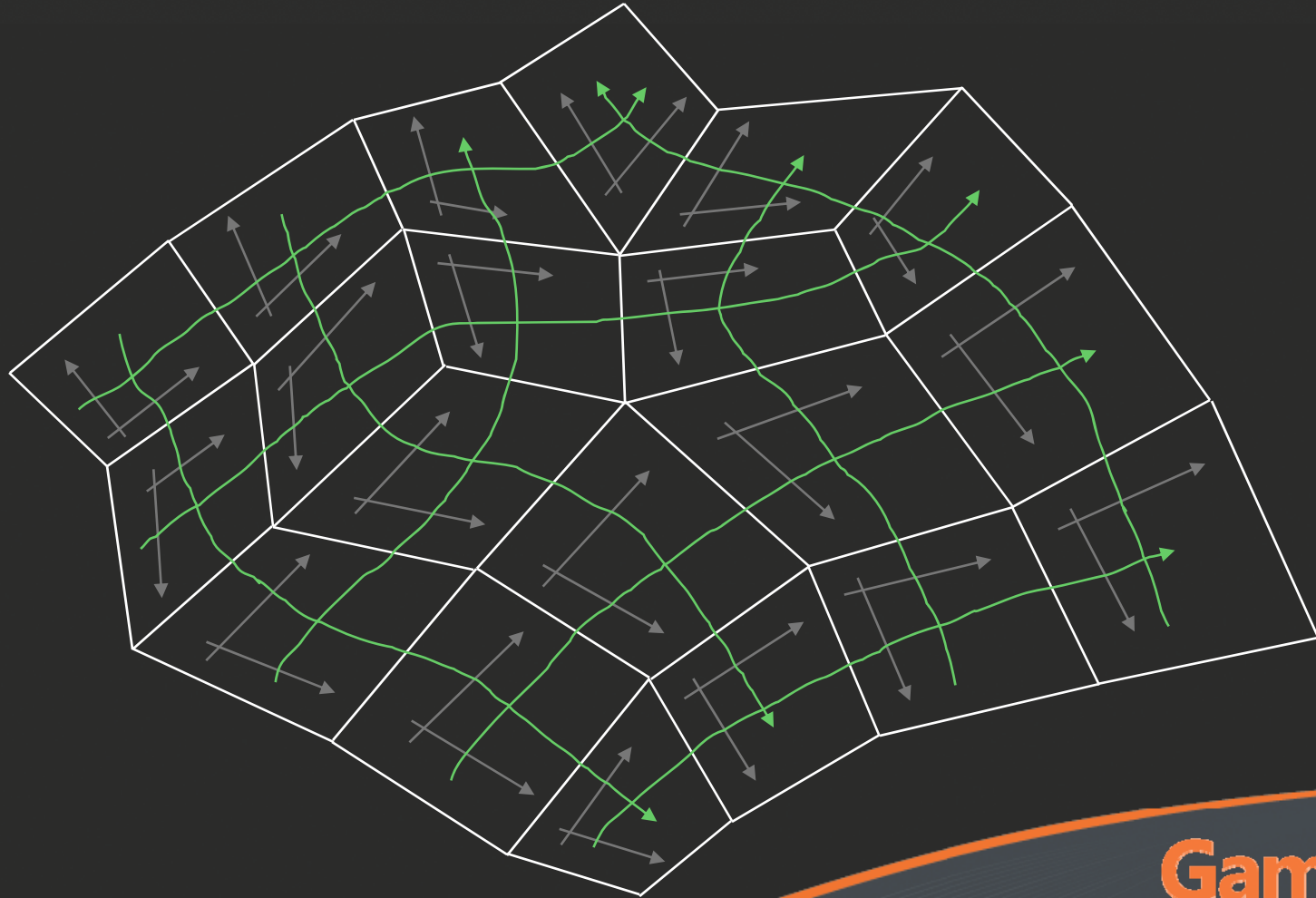
Surface Evaluation

- Reorder patches for consistent adjacency



Surface Evaluation

- Following a greedy algorithm



Bezier Evaluation

- Non-symmetric approach:



- Evaluation order follows parametric direction
- 60 Instructions

Bezier Evaluation

- Non-symmetric approach:



- Evaluation order follows parametric direction
- 60 Instructions

Bezier Evaluation

- Non-symmetric approach:



- Evaluation order follows parametric direction
- 60 Instructions

Bezier Evaluation

- Non-symmetric approach:



- Evaluation order follows parametric direction
- 60 Instructions

Bezier Evaluation

```
float3 bezierPosition(float2 uv, float3 p[16])
{
    float2 B0 = (1 - uv) * (1 - uv) * (1 - uv);
    float2 B1 = 3 * (1 - uv) * (1 - uv) * (uv);
    float2 B2 = 3 * (uv) * (uv) * (1 - uv);
    float2 B3 = (uv) * (uv) * (uv);

    return
        (B0.x * p[ 0] + B1.x * p[ 1] + B2.x * p[ 2] + B3.x * p[ 3]) * B0.y +
        (B0.x * p[ 4] + B1.x * p[ 5] + B2.x * p[ 6] + B3.x * p[ 7]) * B1.y +
        (B0.x * p[ 8] + B1.x * p[ 9] + B2.x * p[10] + B3.x * p[11]) * B2.y +
        (B0.x * p[12] + B1.x * p[13] + B2.x * p[14] + B3.x * p[15]) * B3.y;
}
```



Bezier Evaluation

- This approach only works for quad meshes
- Topology minimization constrains face orientations
- Symmetric evaluation is more flexible

Symmetric Bezier Evaluation

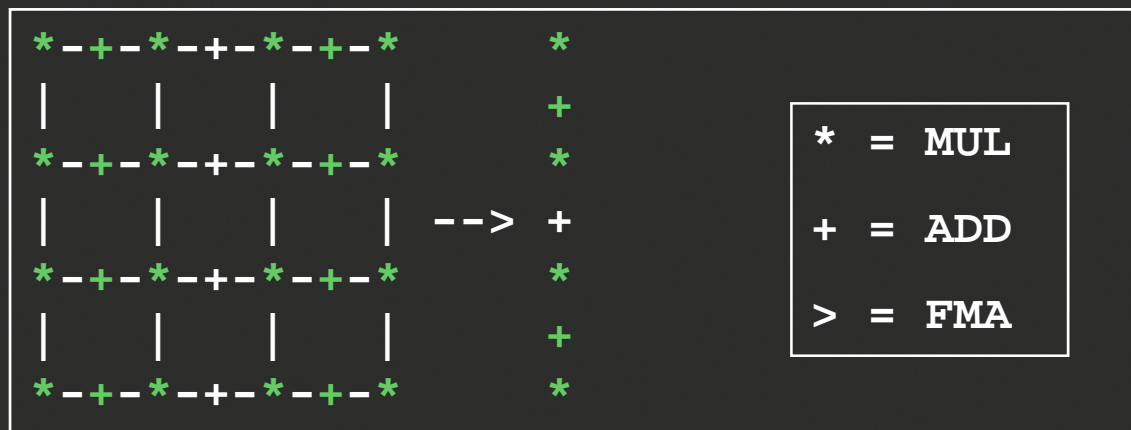
- Disable FMA for symmetric evaluation:



- 105 Instructions

Symmetric Bezier Evaluation

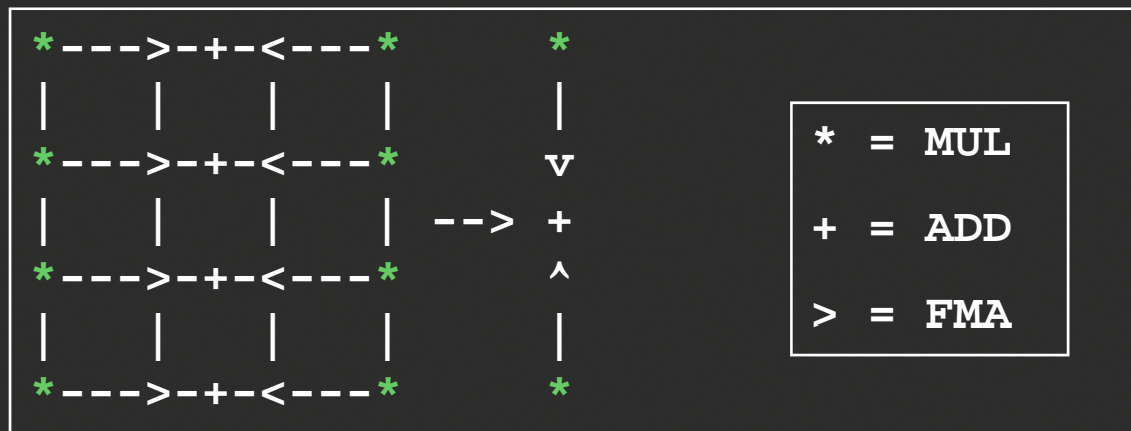
- Disable FMA for symmetric evaluation:



- 105 Instructions

Symmetric Bezier Evaluation

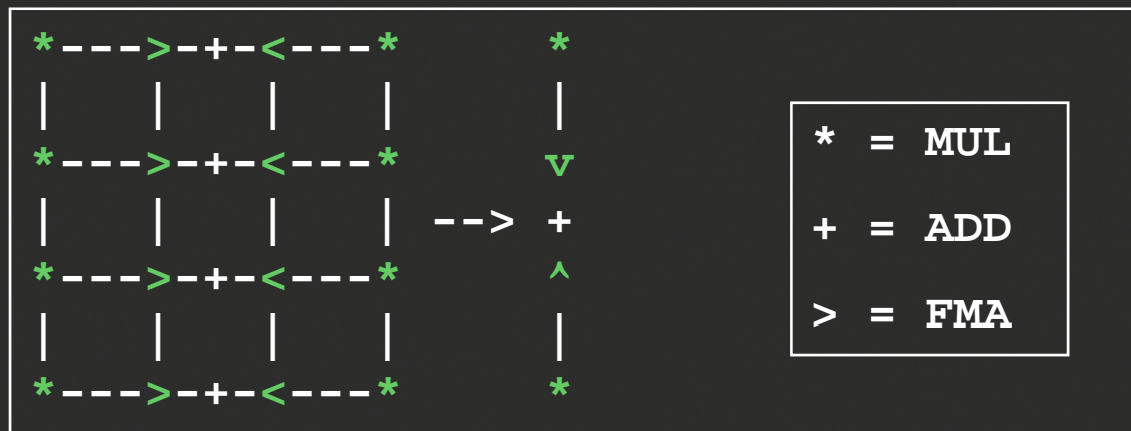
- Use FMA, but still keep symmetry:



- 75 Instructions

Symmetric Bezier Evaluation

- Use FMA, but still keep symmetry:



- 75 Instructions

Symmetric Bezier Evaluation

- Use FMA, but still keep symmetry:



- 75 Instructions

Symmetric Bezier Evaluation

- Symmetry only required on edges:



- 69 Instructions

Symmetric Bezier Evaluation

- Use `mad` and `add` intrinsics

```
float3 w0 = add(  
    mad(B0.x * p[ 0], B1.x, p[ 1]),  
    mad(B3.x * p[ 3], B2.x * p[ 2]));
```

```
float3 w1 = B0.x * p[ 4] + B1.x * p[ 5] + B2.x * p[ 6] + B3.x * p[ 7];  
float3 w2 = B0.x * p[ 8] + B1.x * p[ 9] + B2.x * p[10] + B3.x * p[11];
```

```
float3 w3 = add(  
    mad(B0.x * p[12], B1.x, p[13]),  
    mad(B3.x * p[15], B2.x * p[14]));
```

```
return add(mad(w0 * B0.y, w1, B1.y), mad(w3 * B3.y, w2, B2.y));
```



Symmetric Bezier Evaluation

- Use **precise** to prevent compiler optimizations

```
float3 w0 = [precise] add(  
    mad(B0.x * p[ 0], B1.x, p[ 1]),  
    mad(B3.x * p[ 3], B2.x * p[ 2]));
```

```
float3 w1 = B0.x * p[ 4] + B1.x * p[ 5] + B2.x * p[ 6] + B3.x * p[ 7];  
float3 w2 = B0.x * p[ 8] + B1.x * p[ 9] + B2.x * p[10] + B3.x * p[11];
```

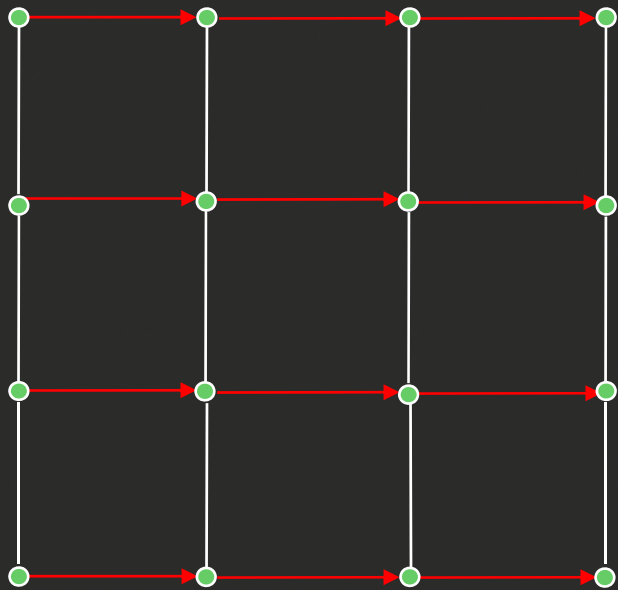
```
float3 w3 = [precise] add(  
    mad(B0.x * p[12], B1.x, p[13]),  
    mad(B3.x * p[15], B2.x * p[14]));
```

```
return [precise] add(mad(w0 * B0.y, w1, B1.y), mad(w3 * B3.y, w2, B2.y));
```

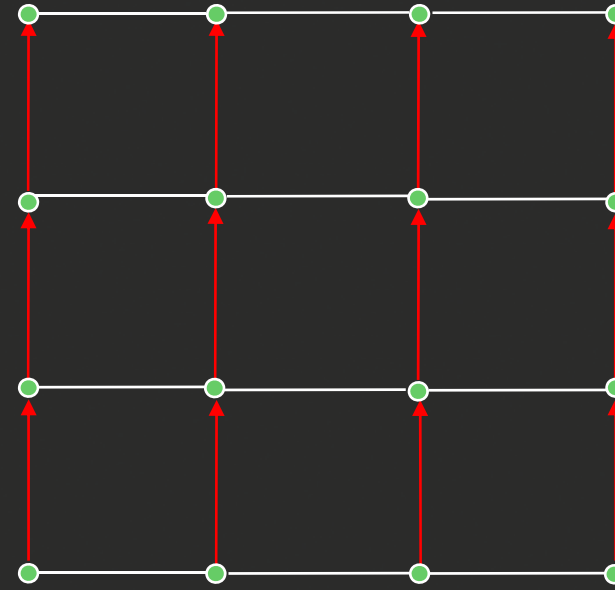


Bezier Patches

- Problem with Bezier Patches:



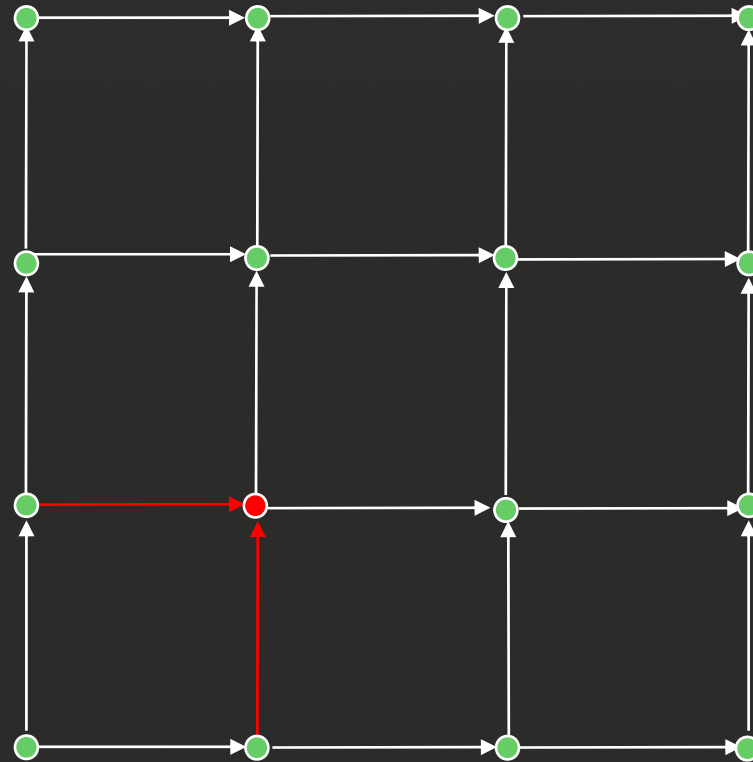
$$\frac{\partial f(u, v)}{\partial u}$$



$$\frac{\partial f(u, v)}{\partial v}$$

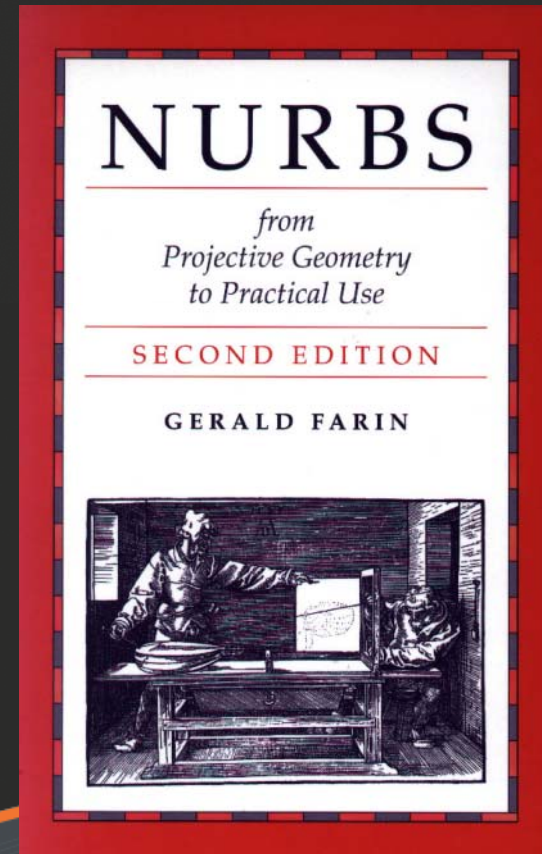
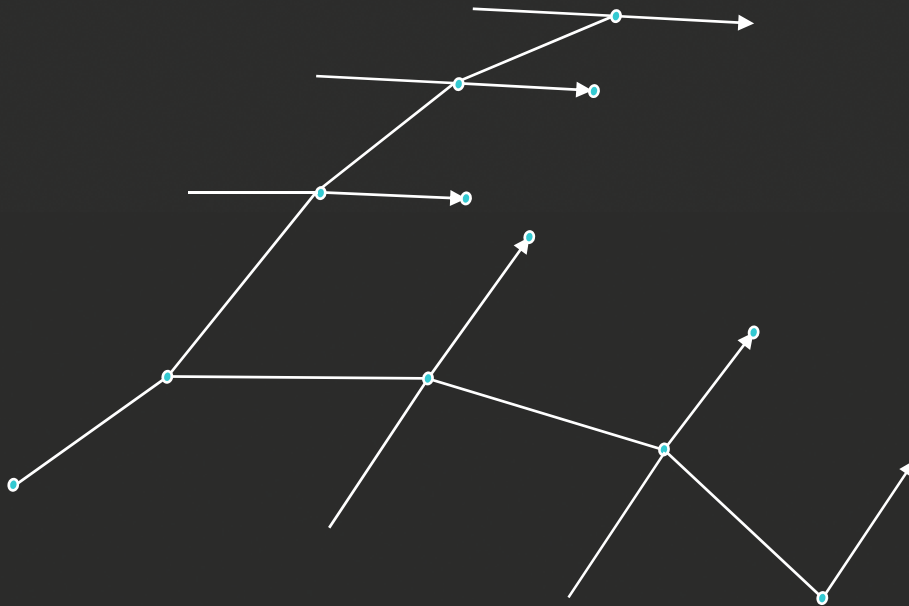
Bezier Patches

- Derivatives along the edges cannot be specified independently



Gregory Patches

- With Bezier patches it's not possible to obtain C1 continuity across all boundaries

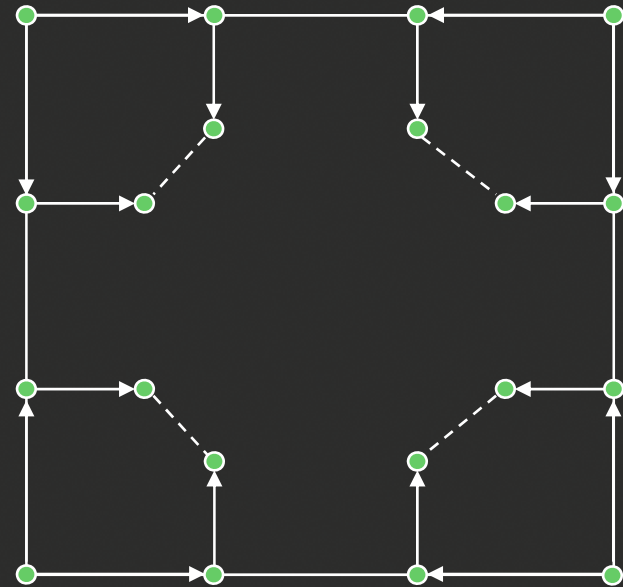


Gregory Patches

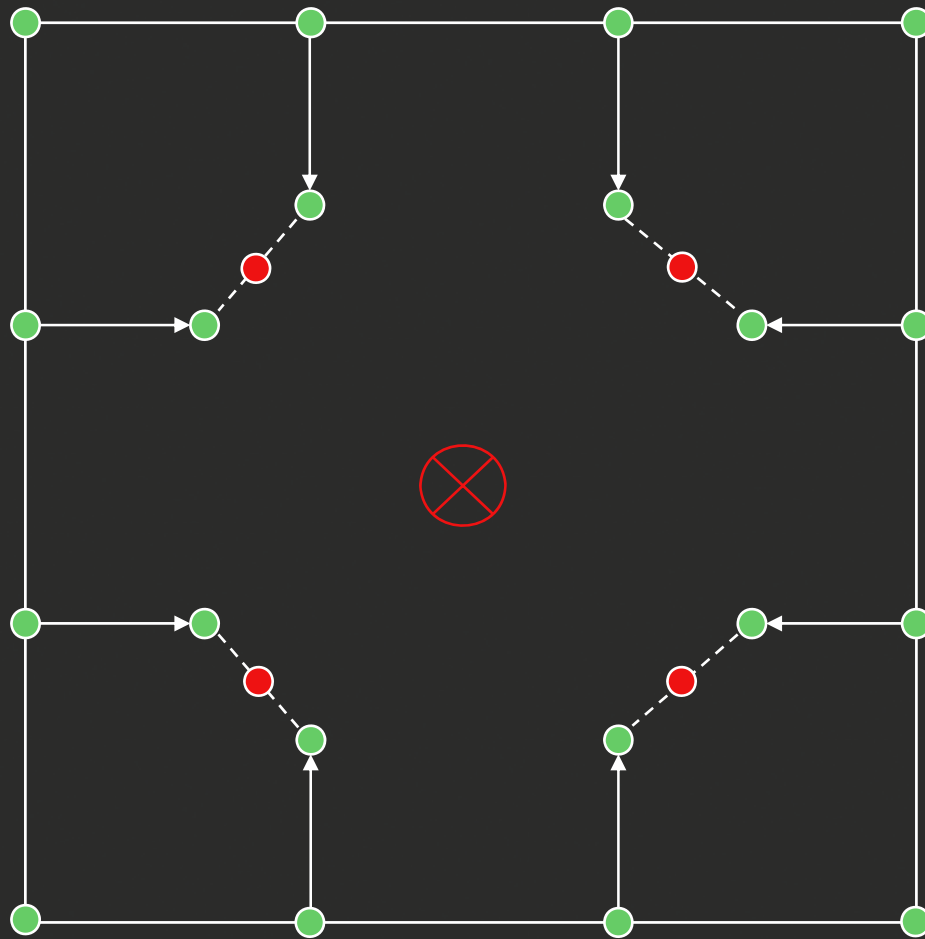
- 20 control points instead of 16
- Evaluated like Bezier where interior control point is computed as:

$$b_{11}(u, v) = \frac{u b_{11u} + v b_{11v}}{u + v}$$

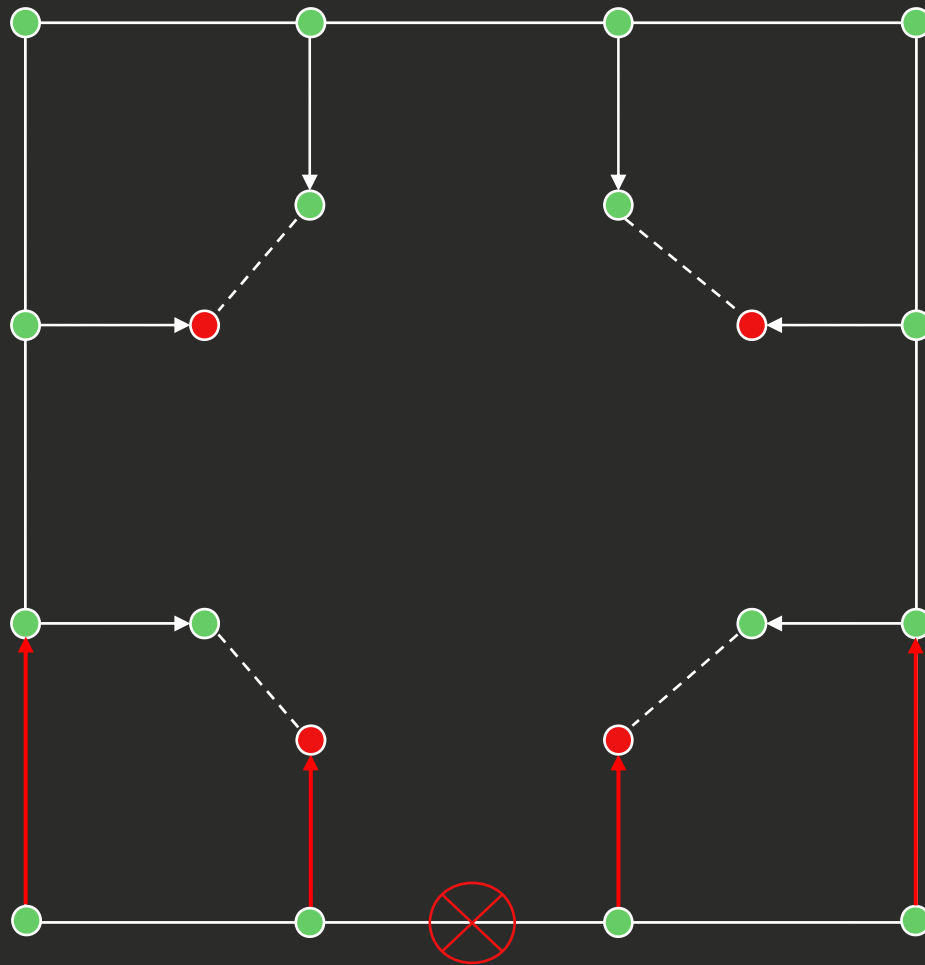
- On regular faces Gregory patch becomes a Bezier patch



Gregory Patches

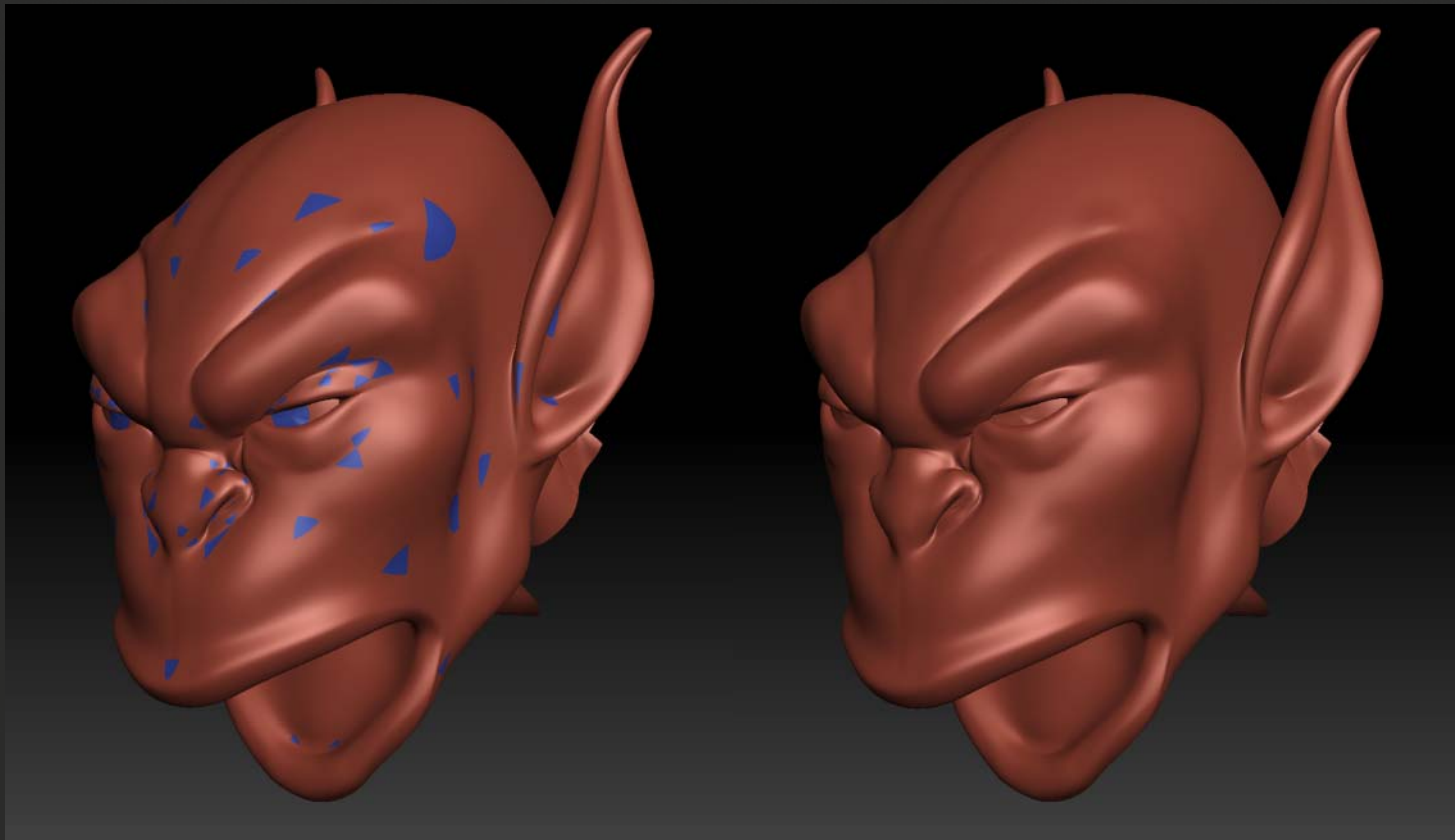


Gregory Patches



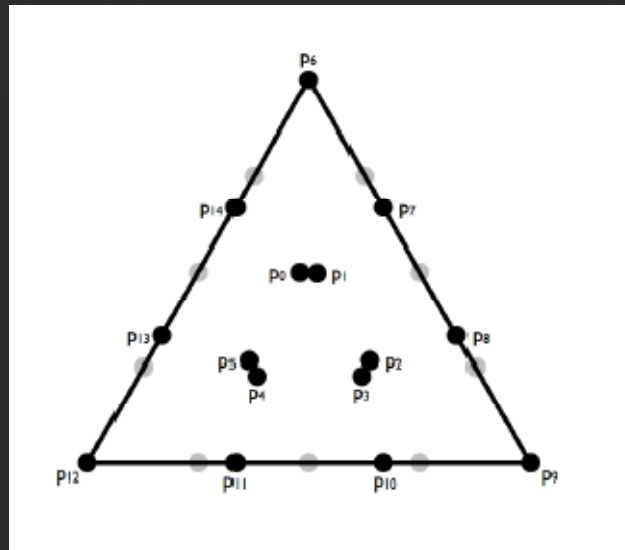
Gregory ACC

- Extended to triangular patches by Denis Kovacs
- Quad-Triangle meshes supported as well



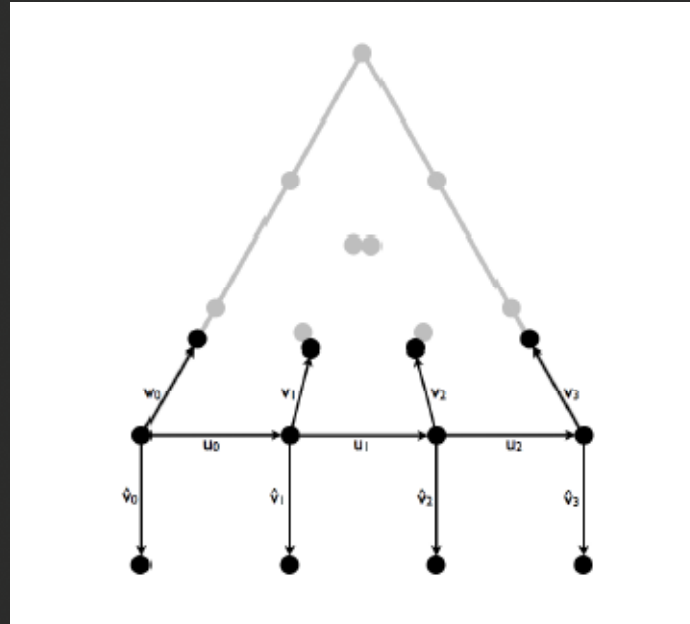
Gregory ACC

- Cubic triangle patches do not have enough degrees of freedom (only one interior control point)
- Use **quartic** patches with **cubic** boundaries



Gregory ACC

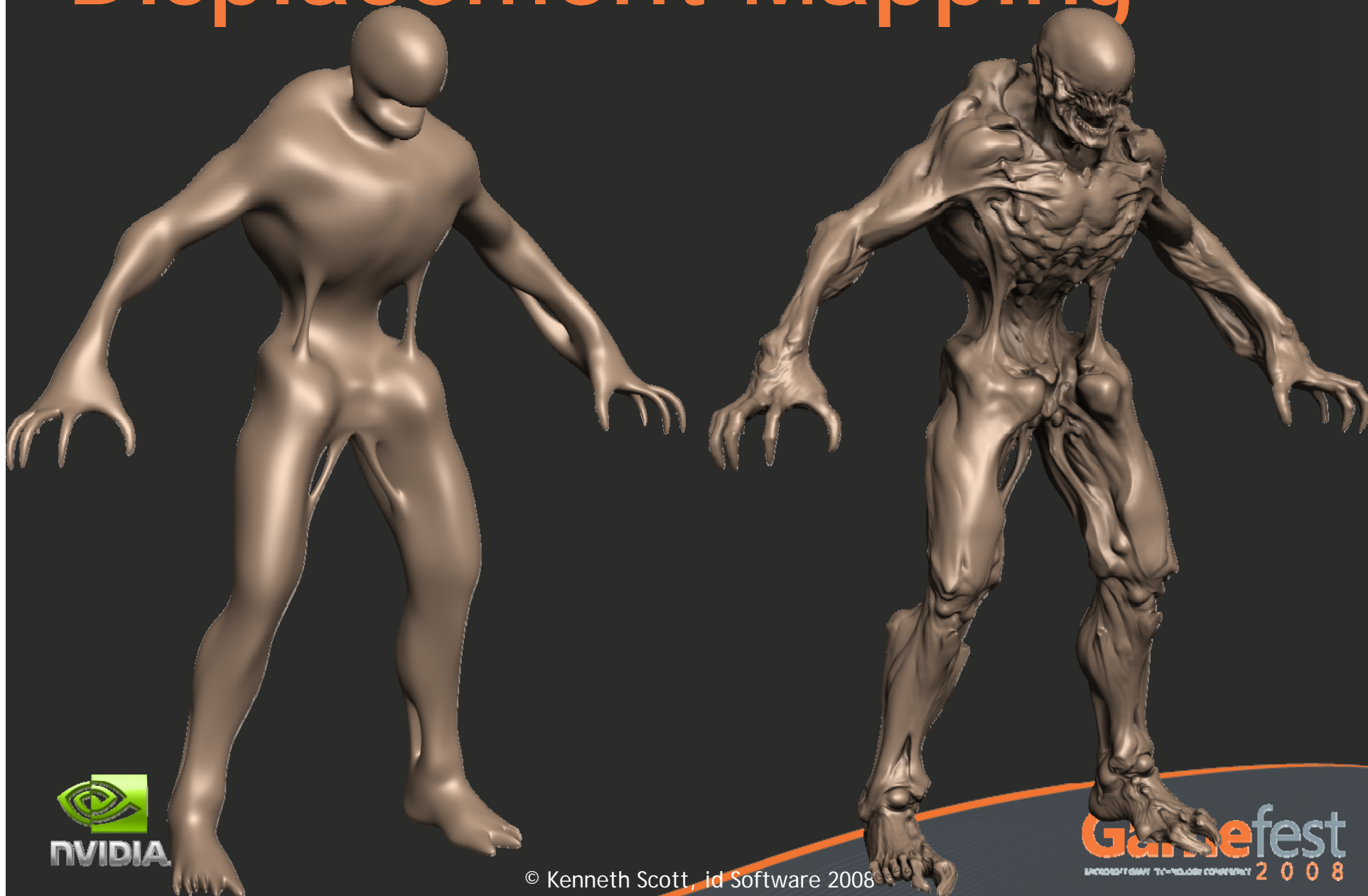
- Duplicate interior control points to satisfy the compatibility condition
- Blended according to parametric distance to edge



Other schemes

- Approximate polar subdivision
 - Prevent ripples around high-valent vertices
- C-Patches & P-Patches
 - More degrees of freedom:
 - C2 continuity
 - Sharpness adjustment
 - Triangles, Quads, and Pents
 - Evaluation is only slightly more expensive

Displacement Mapping

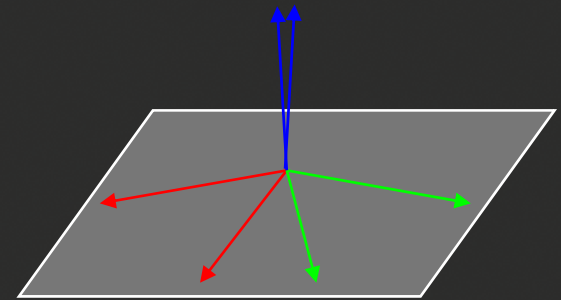


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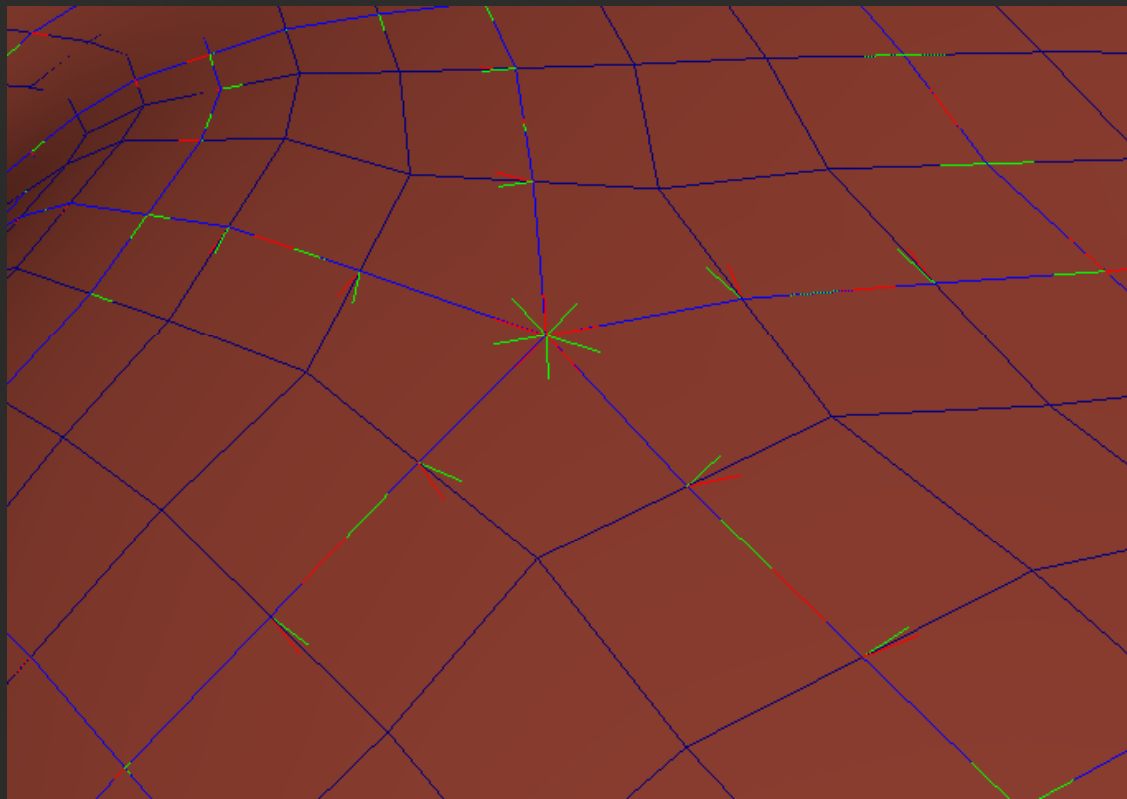
Displacement Maps

- Crack-free displacement maps
- Consistent normal evaluation
- Watertight texture sampling



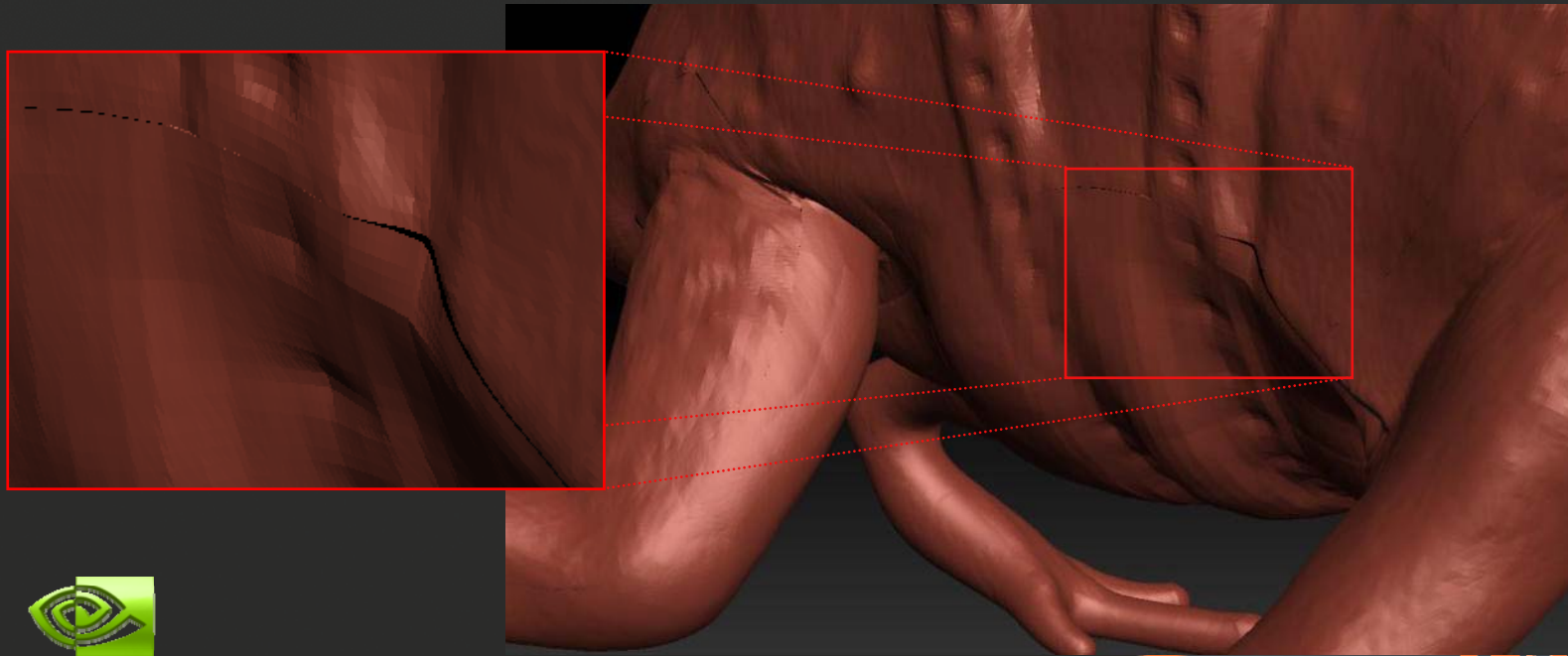
Consistent Normal Evaluation

- Control tangents along edges are not symmetric:



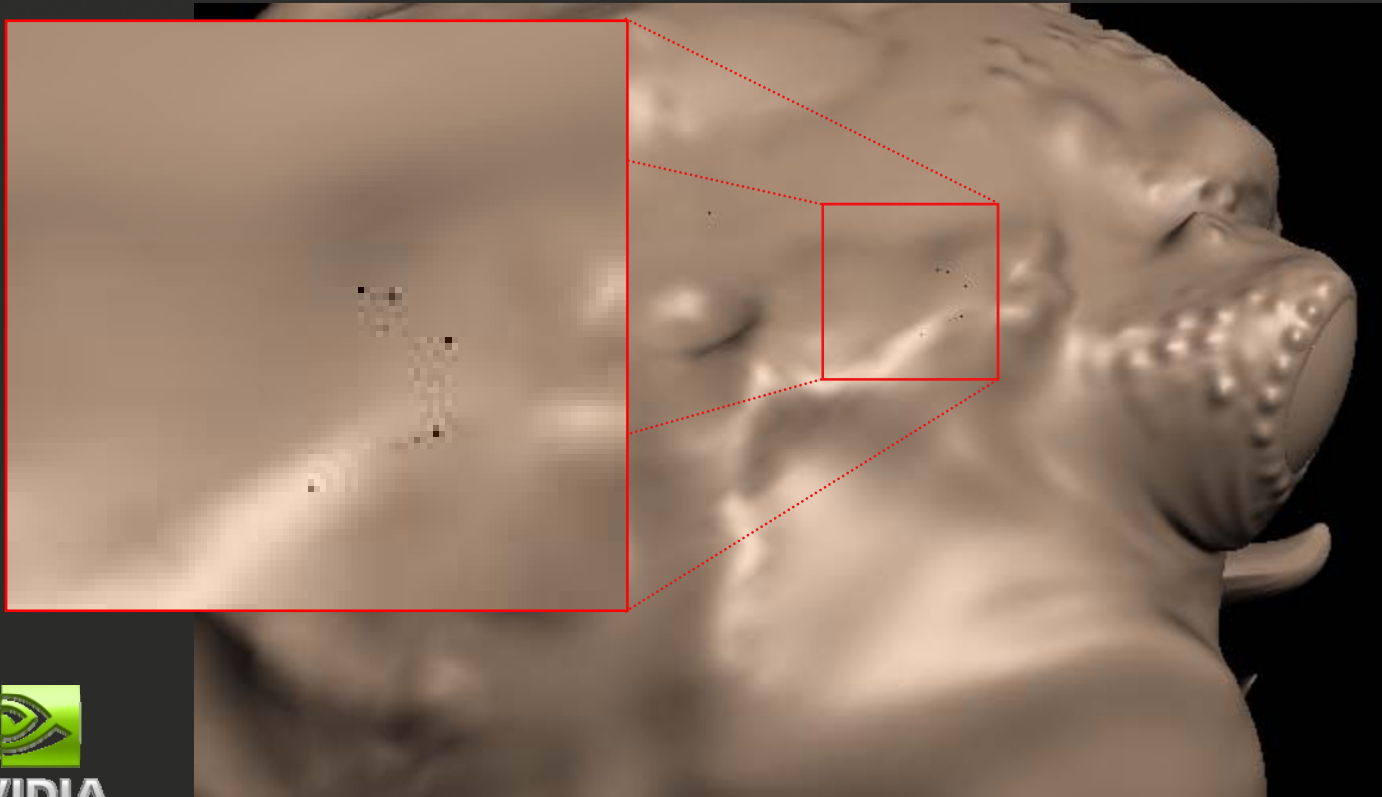
Watertight Texture Sampling

- Texture seams cause holes in the mesh!
- Due to bilinear discontinuities
- Varying floating point precision on different regions of the texture map



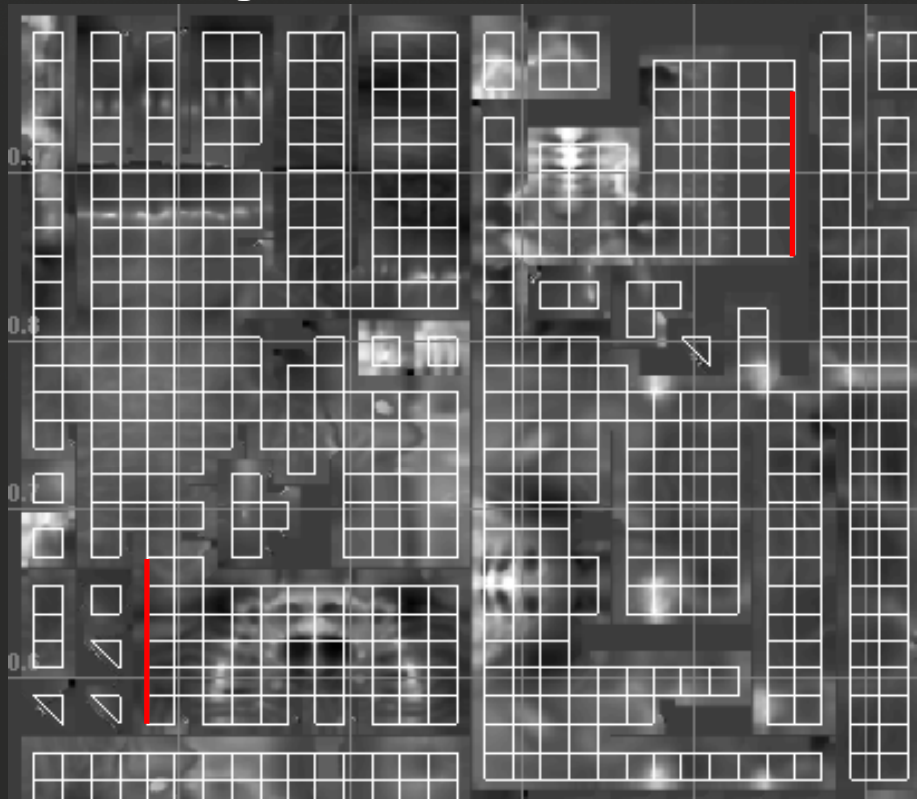
Watertight Texture Sampling

- Seamless parameterizations remove bilinear artifacts, but do not solve floating point precision issues



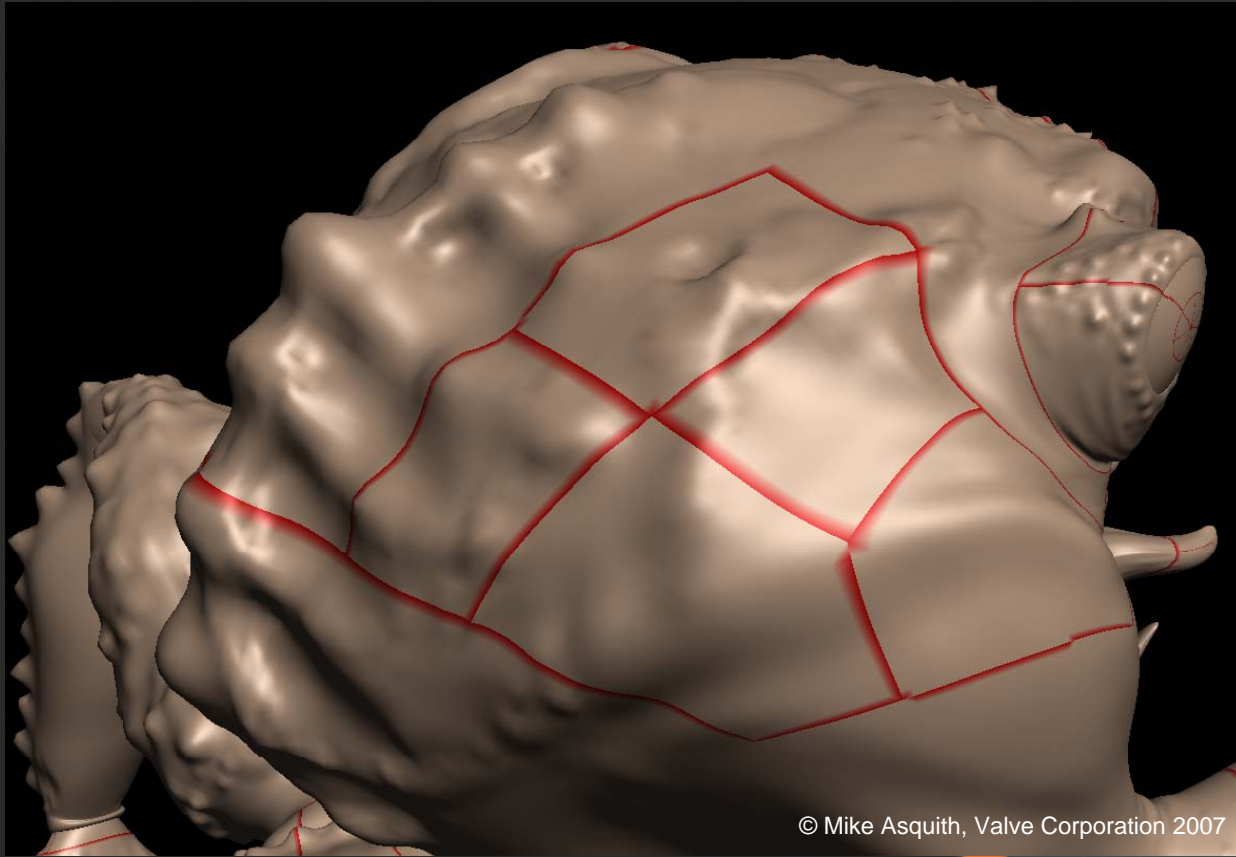
Watertight Texture Sampling

- Texture coordinate interpolation yields different result depending on location of the seam edges:



Watertight Texture Sampling

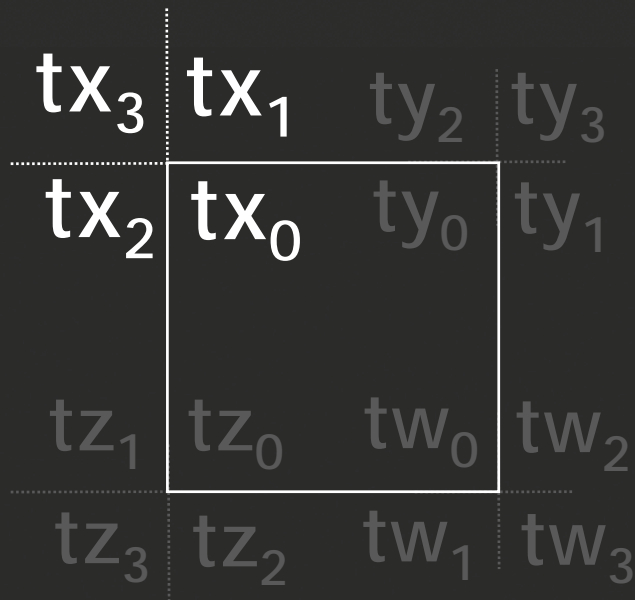
- Solution: define edge and corner ownership



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Watertight Texture Sampling

- Store 4 texture coordinates per vertex
 - 16 per patch



```
// float2 tx[4], ty[4], tz[4], tw[4];
```

```
int ix = 2 * (uv.x == 1) + (uv.y == 1);  
int iy = 2 * (uv.y == 1) + (uv.x == 0);  
int iz = 2 * (uv.x == 0) + (uv.y == 0);  
int iw = 2 * (uv.y == 0) + (uv.x == 1);
```

```
float2 tc = w.x * tx[ix] +  
          w.y * ty[iy] +  
          w.z * tz[iz] +  
          w.w * tw[iw];
```


Content Creation

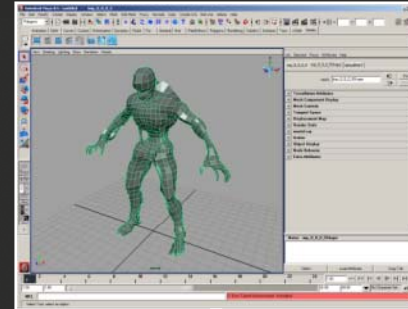


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Production Pipeline

- Modeling Tools
 - Base surface
- Sculpting Tools
 - Detailed mesh
- Baker Tools
 - Normal, displacement, occlusion, and other maps



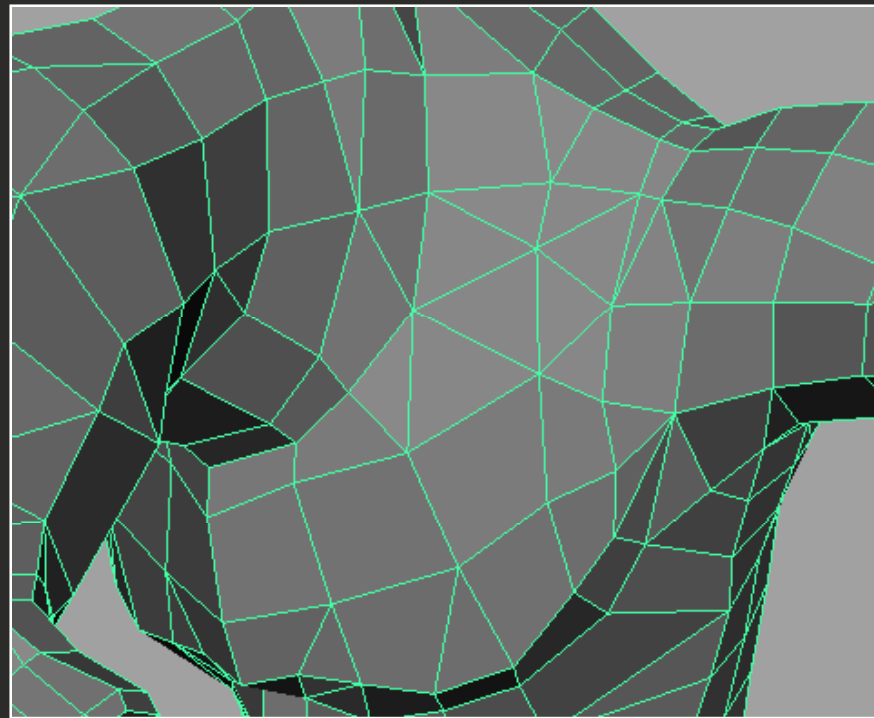
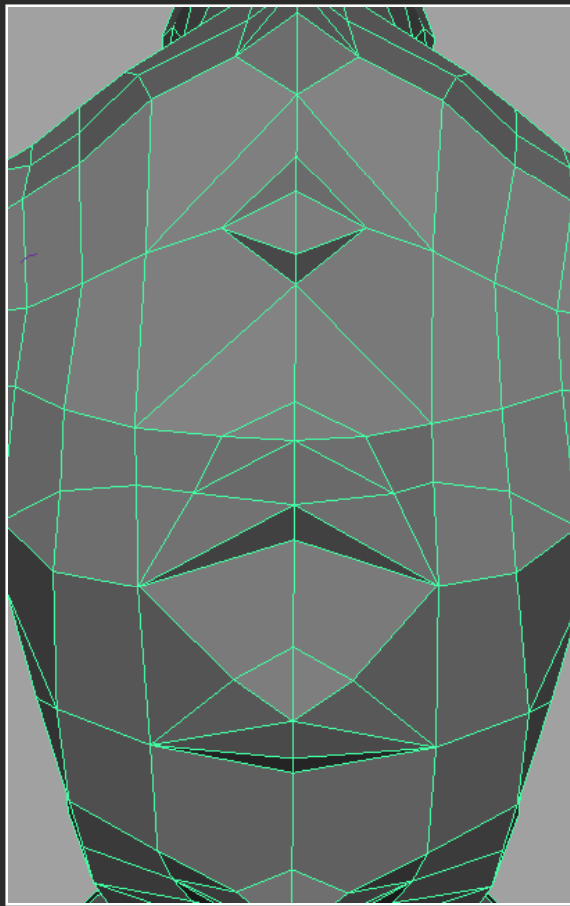
Modeling

- Performance depends on number of topology combinations
- Optimization guidelines:
 - Eliminate triangles (Quad only meshes)
 - Close holes (Avoid open meshes)
 - Reduce number of extraordinary vertices
 - Decrease number of patches to the minimum
- Try to create uniform, regular meshes



Topology Optimization

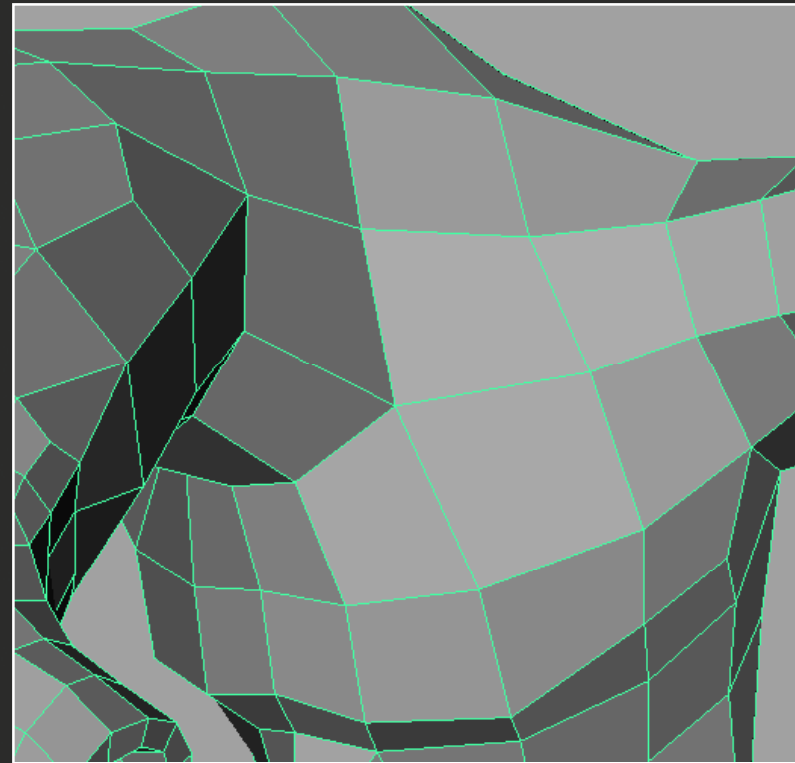
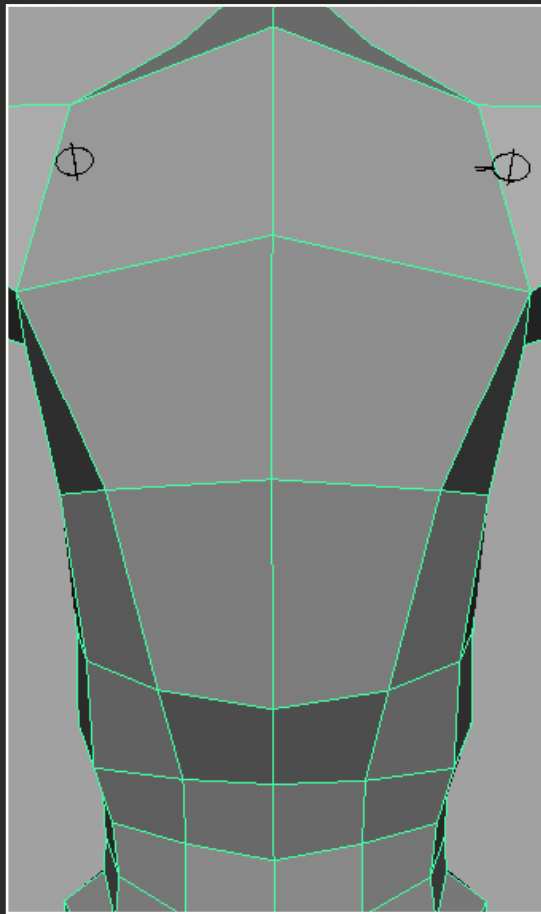
- 105 topology combinations



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Topology Optimization

- 23 topology combinations



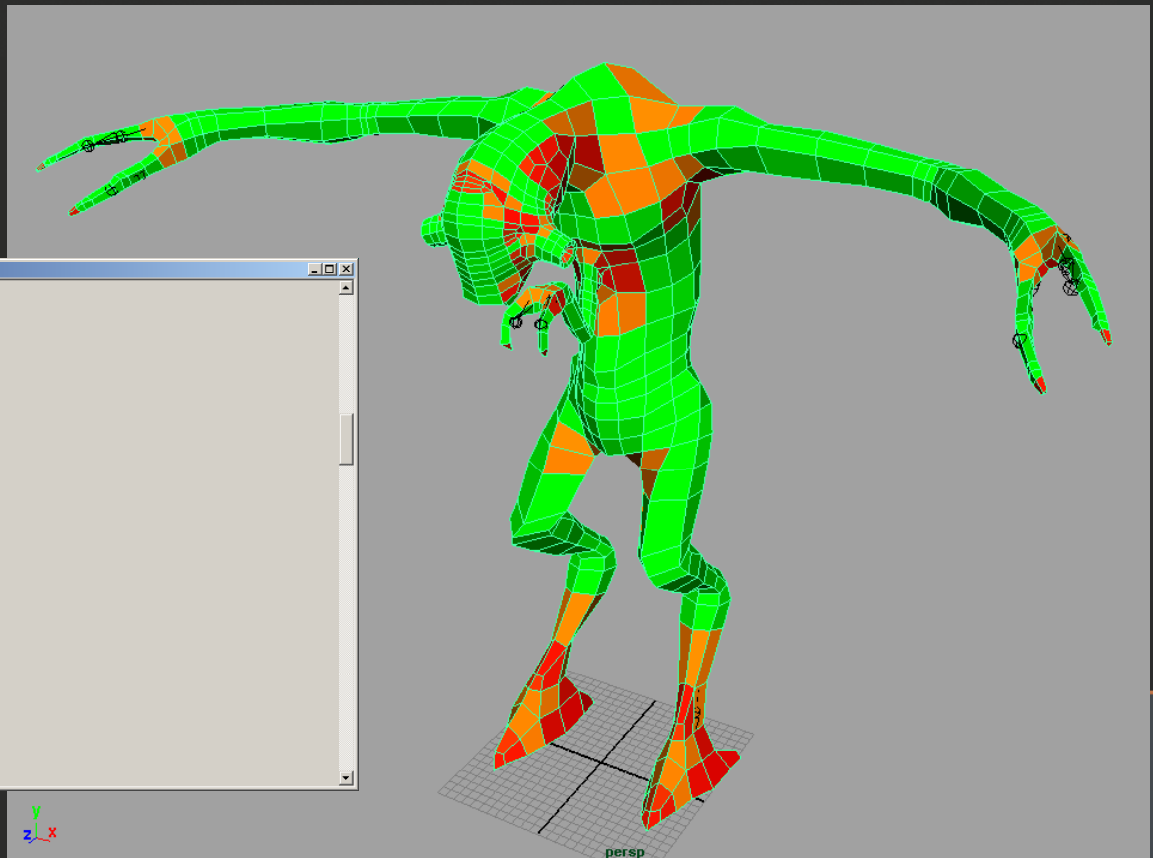
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Topology Optimization

- Topology visualization tool (nvAnalyze)
- Maya plugin that highlights faces that damage mesh quality the most

```
Output Window
Patch Configuration Info:
patch count = 2574
triangle count = 820
quad count = 1738
polygon count = 16
regular patch count = 690
boundary patch count = 0
regular boundary patch count = 0
patch configuration count = 220

Interior Patches:
- 7 4 4 3 : 1
- 4 3 4 4 : 1
- 8 4 4 5 : 1
- 4 6 4 6 : 1
- 0 6 6 7 : 1
- 0 6 6 8 : 1
- 8 8 4 4 : 1
- 0 6 4 5 : 34
- 5 5 4 4 : 26
- 5 4 4 4 : 117
- 6 4 4 5 : 17
- 4 4 4 4 : 690
- 7 4 4 4 : 7
- 4 5 4 4 : 112
- 6 5 4 5 : 2
- 4 6 4 4 : 42
- 0 5 4 5 : 39
- 4 5 4 5 : 16
- 0 6 4 4 : 27
- 0 4 4 5 : 42
- 4 4 4 5 : 113
- 4 4 6 4 : 41
- 0 4 6 8 : 2
```



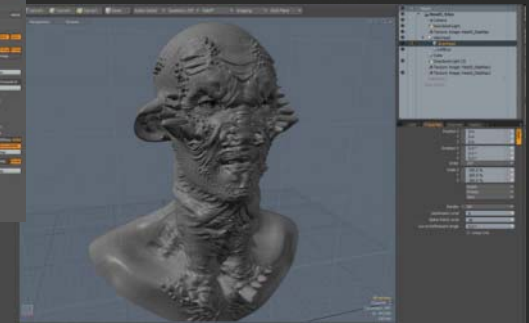
NVIDIA Mesh Processing Tool

- Successor of **NVMeshMender** and **NVTriStrip** but for subdivision surfaces:
 - Reorder faces for consistent adjacencies
 - Minimize topology combinations
 - Pre-compute stencils for different approximation schemes
 - Compute texture coordinates for watertight texture sampling
 - Optimize vertex and face order for best performance
 - And more!



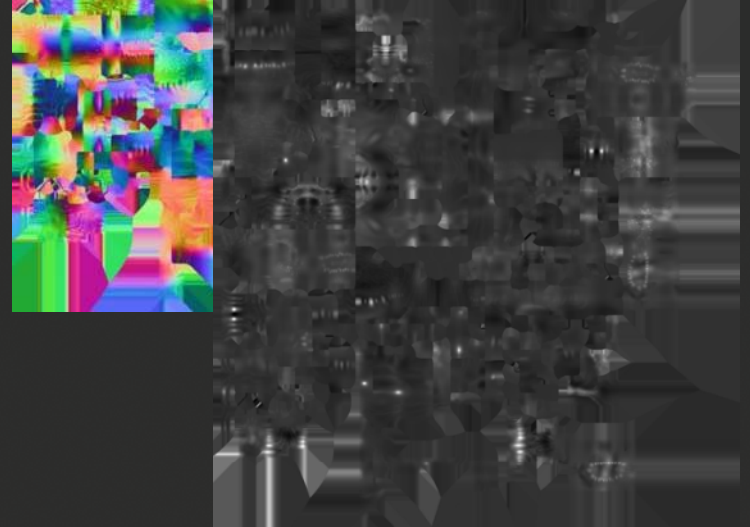
Sculpting

- Many tools available:
 - Autodesk® *Mudbox*™
 - Pixologic ZBrush®
 - modo™, Silo, Blender, etc.



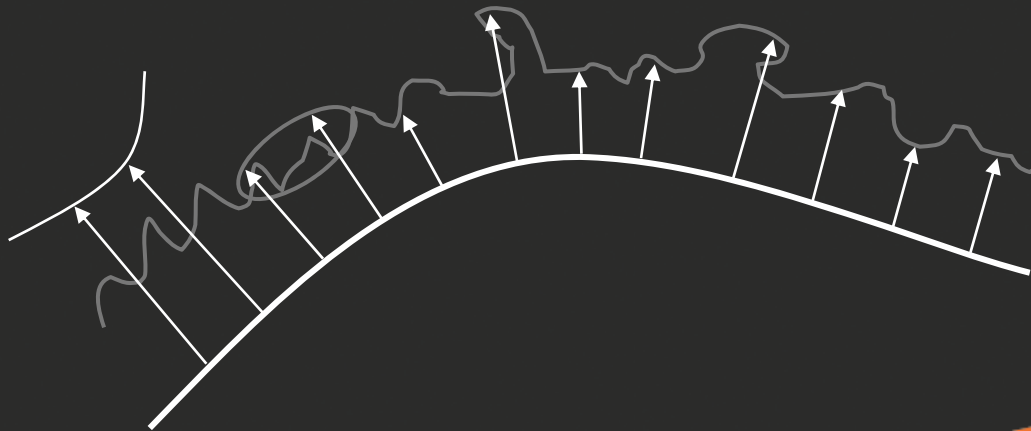
Baker Tools

- Many options:
 - xNormal™
 - Mudbox™, ZMapper
 - Melody™, etc.
 - PolyBump™, etc.
- Two approaches
 - Ray casting
 - Dual parameterization



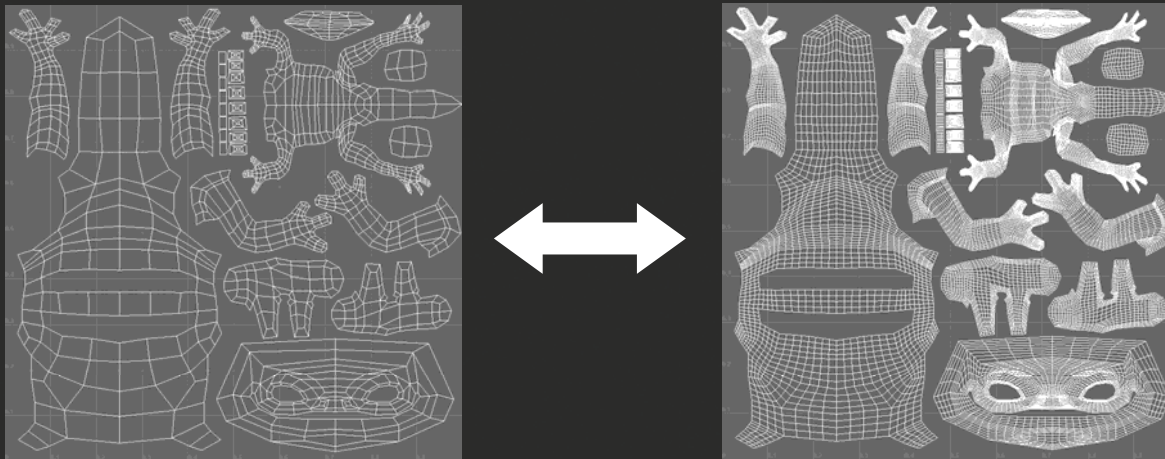
Capturing Attributes

- Ray casting
 - Can sample complex meshes made of multiple pieces
 - Produces better scalar displacements
 - Occasional artifacts (missing rays, double hits)
 - Require artist supervision and tweaking



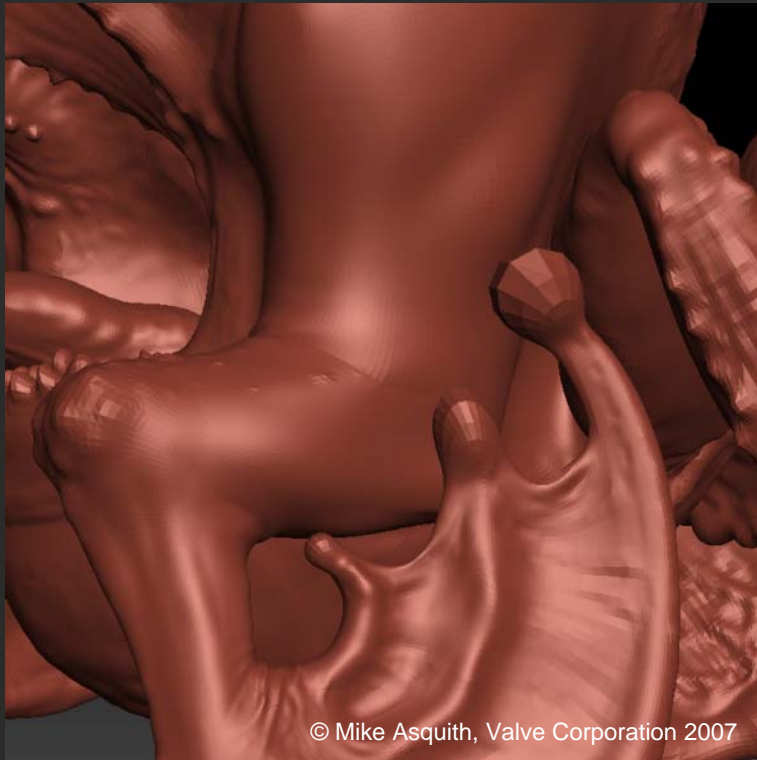
Capturing Attributes

- Dual parameterization
 - Much faster, easy to implement
 - Higher quality vector displacements
 - Artifact free, no artist supervision required
 - Inaccurate scalar displacements
 - Low and high res meshes must have same topology

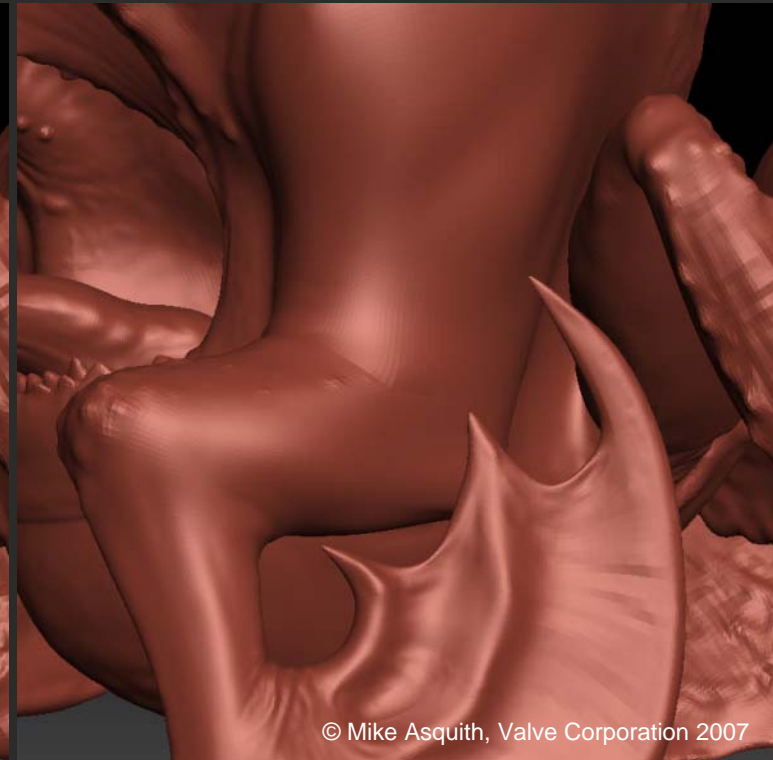


Vector Displacements

- Native representation of most sculpting tools



1D Displacements



3D Displacements



NVIDIA Baker Tool

- Uses dual parameterization to extract:
 - Normal and displacement maps
 - Only tool that generates vector displacements
 - Occlusion maps, and more!
- No other tool supports custom base surfaces:
 - Bezier ACC
 - Gregory ACC
 - Triangle meshes



NVIDIA Baker Tool

- Uses optimized Monte Carlo Raytracer
- Can be easily extended to support:
 - Bent normals
 - Spherical harmonic PRTs
 - etc.
- Full source code will be openly available



Thanks

- Bay Raitt, Mike Asquith, Valve Corporation
- Kenneth Scott, id Software



Q & A

- Ignacio Castaño icastano@nvidia.com





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